



## Davide Scaramuzza

Professor

Director of the Robotics and Perception Group

Department of Informatics  
University of Zurich  
Andreasstrasse 15, 2.10,  
Zurich, 8050, Switzerland

Nationality: Italian

Place of Birth: Terni, Italy

Languages: Italian (native), English, French, German, Spanish

Homepage: [https://rpg.ifi.uzh.ch/people\\_scaramuzza.html](https://rpg.ifi.uzh.ch/people_scaramuzza.html)

YouTube: <https://www.youtube.com/ailabRPG>

Google Scholar: [scholar.google.com/citations?hl=en&user=SC9wV2kAAAAJ](https://scholar.google.com/citations?hl=en&user=SC9wV2kAAAAJ)

Citations: > 38,000 - H-Index: 93 - H10 index: 204

## Education

03/2005 - 02/2008



**PhD in Robotics and Computer Vision, ETH Zurich.**

Advisor: Prof. Roland Siegwart. Reviewers: Luc Van Gool and Patrick Rives.

*Robotdalen Scientific Award (20k EUR) and finalist of the George Giralto PhD Award.*

09/1999 - 07/2004



**Laurea Degree (equivalent to Bachelor + Master) in Electronics and Information Engineering, University of Perugia, Italy.**

GPA: 30/30, Distinction: 110/110, *Summa Cum Laude and Dignity of Printing +*

*Winner of the Federcomin Master Thesis Award, given by the Italian Minister of Innovation.*

## Academic Positions

09/2017 – Today



**Tenured Associate Professor of Robotics and Perception, Dep. of Informatics, University of Zurich**

Director of the Robotics and Perception Group

Founder and Director of the Master in Artificial Intelligence at the University of Zurich

04/2019 – 6/2019

**Stanford University**

**Visiting Associate Professor, Stanford University**

Hosts: Prof. Mac Schwager and Prof. Marco Pavone

02/2012 – 09/2017



**Assistant Professor of Robotics & Perception, University of Zurich**

01/2011 – 01/2012



**Post-doc and EU project coordinator. GRASP Lab, University of Pennsylvania**

Advisor: Prof. Vijay Kumar and Prof. Kostas Daniilidis

03/2008 – 12/2010



**Post-doc, Lecturer, EU project coordinator, and Project Leader. ETH Zurich**

Advisor: Prof. Roland Siegwart

10/2009 – 12/2009



**Invited Research Scientist at the Council for Scientific and Industrial Research (CSIR), Pretoria, South Africa, Employer: Dr. Simukai Utete**

07/2006 – 02/2008



**Research and Teaching Assistant (PhD student). ETH Zurich,**

Advisor: Prof. Roland Siegwart

02/2005 – 07/2006



**Research and Teaching Assistant (PhD student). EPFL Lausanne,**

Advisor: Prof. Roland Siegwart

## Entrepreneurial Achievements

- **SUIND:** Safety device for commercial drones. Ongoing. Backed by Venture Kick, NCCR, and SNSF BRIDGE.
- **Zurich Eye:** Visual-inertial SLAM solutions for mobile robots. Now **Facebook-Meta-Oculus Zurich**.
- **Strategic Advisory** role at Dacuda, now **Magic Leap Zurich**.

## Other Academic Activities

- Director of the Robotics and Perception Group (since 2012)
- Founder and Director of the Master in Artificial Intelligence at the University of Zurich, Dep. of Informatics (since 2021)
- Teaching and Ph.D. committee at the University of Zurich, Dep. of Informatics (2018-2022)
- Head of the NCCR Rescue Robotics Grand Challenge (2017 to 2022).

## My Research Team

My research team (the Robotics and Perception Group) currently consists of 9 Ph.D. students, 2 Postdocs, 1 engineer, and four research assistants. I also regularly host researchers from top research institutions (e.g., MIT, Caltech, INRIA, Max Planck), who stay for several months. Lab webpage: <https://rpg.ifi.uzh.ch/>



## Paper Awards

- 2022 **NCCR Most Impactful Paper award** in 12 years for the RAL'16 paper on learning visual navigation in forests
- 2022 **IEEE RAL Best Paper Award** for the paper on drone flight despite rotor failure using onboard sensors
- 2021 **NASA Tech Briefs Award** for the paper on drone flight despite rotor failure using onboard sensors
- 2021 **IEEE Transactions on Robotics' Best Paper Award** finalist for the paper "Deep Drone Racing"
- 2020 **RSS Best Systems Paper Award** for the paper "AlphaPilot: Autonomous Drone Racing"
- 2020 **RSS Best Paper Award Finalist** for the paper "Deep Drone Acrobatics"
- 2019 **NASA Tech Briefs Award** for the RAL'19 paper "The Foldable Drone"
- 2019 **IEEE RAL Best Paper Award** finalist for the paper "Ultimate SLAM"
- 2019 **ICRA Workshop on SLAM Benchmarking Best Paper Award** for the paper on trajectory evaluation for SLAM
- 2018 **CORL Best System Paper Award** for the paper on deep drone racing
- 2018 **IEEE Transactions on Robotics' Best Paper Award** for the paper on on-manifold preintegration for VIO
- 2017 **IROS 2017 Paper Award finalist** in the category Rescue Robotics for the paper on rapid exploration
- 2017 **RSS' 17 Best Student Paper Award Finalist** for the paper on agile flight
- 2016 **IROS'16 Best Application Paper Finalist** for the paper on event-based feature tracking
- 2016 **BMVC'16 Best Industry Paper Award** for the paper on event-based multi-view stereo
- 2016 **AAAI'16 Best Video Award Finalist** for the RAL'16 paper on learning visual navigation in forests
- 2015 **Best Paper Award Finalist at RSS'15** for the paper on on manifold preintegration for VIO

## Other Awards (ERC, career awards, industry awards, etc.)

- 2023 **IEEE Featured author**
- 2022 **1,000 World's Top Computer Scientists by research.com: Davide Scaramuzza** [\[link\]](#)
- 2021 **Aminer 100 Most Influential Robotics Scholar (world ranking: 14): Davide Scaramuzza**
- 2019 **ERC Consolidator Grant (2 M EUR)**
- 2019 **AlphaPilot Drone Racing World Championship, 2<sup>nd</sup> place winner**
- 2019 **Facebook Distinguished Faculty Award**
- 2019 **Elevation to the degree of IEEE Senior Member**
- 2019 **Drone Hero Contest 2019 – EU's most innovative drone contest (for the foldable drone)**
- 2018 **IROS Autonomous Drone Racing Competition, 1<sup>st</sup> place winner**
- 2018 **Intel Network of Intelligent System Award**
- 2018 **Qualcomm Innovation Award**
- 2017 **Misha Mahowald Prize** for Neuromorphic Engineering for *pathbreaking applications of event cameras to robotics*
- 2017 **Intel Network of Intelligent System Award**
- 2017 **EU Robotics Transfer Award with Fotokite**
- 2016 **Qualcomm Innovation Award**



European Research Council  
Established by the European Commission



- 2014 **ERC-SNSF Starting Grant** (1.6 M EUR)
- 2014 **IEEE Robotics and Automation Early Career Award** for *contributions to robot vision and vision-based drones*
- 2014 **KUKA Innovation Award** (worldwide competition, 20,000 EUR)
- 2014 **Google Faculty Research Award** (1<sup>st</sup> time outside of USA in robotics)
- 2012 **European Young Researcher Award** - Sponsored by EU and Euroscience
- 2010 **George Giralt PhD Award** finalist, 2010 - Sponsored by EuRobotics
- 2009 **ROBOTDALEN Best PhD Thesis Award in Robotics** (20k EUR). Sponsored by EU, IEEE, ABB, and VOLVO.
- 2009 **European Micro Aerial Vehicle competition (EMAV)**, 2nd place winner – TU Delft
- 2005 **FEDERCOMIN-Aica** Italian Best Master Thesis Award, (5k EUR), given by the Italian Minister of Innovation.
- 2004 **Ternana Opera Educatrice** - (800 Euros in prize money) as best Master student in his home University
- 1998 **Italian Mathematical Olympiads**, finalist Umbria region, Italy. Participated in the national competition.



## Promotion by the President of the University of Zurich

**Six consecutive promotions** by the UZH rectors Andreas Fischer, Michael Hengartner, Michael Schaeppman in 2013, 2014, 2015, 2018, 2020, 2021 for outstanding achievements.

## Promotion of Young Researchers

- 2022 **Czech Science Foundation's Junior Star Award** to Dr. Robert Penicka (1 M Euros, equivalent to ERC)
- 2022 **NCCR Robotics Best Master thesis award** to Michelle Rueeg
- 2022 **Georges Giralt Best PhD Thesis Award** (winner) to Antonio Loquercio
- 2021 **Georges Giralt Best PhD Thesis Award** finalist to Zichao Zhang
- 2021 **UZH Annual Award** to **Dr. Zichao Zhang** for best PhD dissertation
- 2021 **UZH FAN Award** (100k CHF) to Dr. Christian Pfeiffer
- 2021 **UZH Forschungskredit** (60k CHF) to Mathias Gehrig
- 2020 **ETH Medal** to Tim Taubner for his Master Thesis
- 2019 **ETH Medal** to Daniel Gehrig for his Master Thesis
- 2020 **Georges Giralt Best PhD Thesis Award** finalist to Henri Rebecq
- 2019 **Dr. Guillermo Gallego appointed Faculty at TU Berlin**
- 2019 **AlphaPilot Drone Racing World Championship**, 2<sup>nd</sup> place winner
- 2019 **UZH Forschungskredit** (60k CHF) to Titus Cieslewski
- 2018 **Qualcomm Innovation Award** (40k USD) to Henri Rebecq
- 2018 **Georges Giralt Best PhD Thesis Award** finalist to Christian Forster
- 2016 **ETH Fritz-Kutter ETH Award** (10k CHF) to Timo Horstschaefter
- 2016 **Qualcomm Innovation Award** (40k USD) to Elias Mueggler
- 2015 **UZH Forschungskredit** (100k CHF) to Dr. Guillermo Gallego
- 2014 **ETH Fritz-Kutter ETH Award** (10k CHF) to Basil Huber
- 2014 **UZH Forschungskredit** (60k CHF) to Christian Forster
- 2014 **UZH Forschungskredit** (100k CHF) to Dr. Reza Sabzevari
- 2013 **KUKA Best Student Project Award 2013** to Benjamin Keiser



**TEDx Talk** - 2012 - Swiss National TV studios: <https://youtu.be/KQpKQXU7dkM>



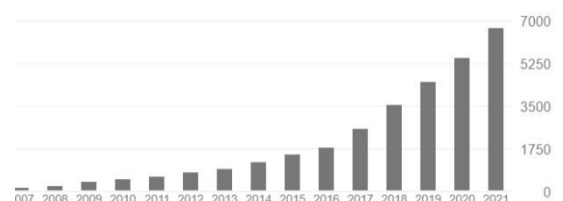
## Citation Indices

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**Scholar i10-index:** 204

<http://scholar.google.com/citations?user=SC9wV2kAAAAJ&hl=en>



## Teaching Activities

2022 - today	University of Zurich, "Machine Learning - an Interdisciplinary Introduction", 60 students.
2016 - today	ETH and University of Zurich, "Vision algorithms for mobile robotics", Master's. 200 students.
2018 - today	University of Zurich, "Foundations of Computing I", 1 <sup>st</sup> year Bachelor's. 300 students
2018 - today	University of Zürich, Certificate of Advanced Study (CAS) – Block course on Mobile Robotics
2015 - today	Hochschule für Wirtschaft Zürich, CAS, – Block Course on Mobile Robotics
2017 - 2021	Basics of Instrumentations and Measurements, Master's, 50 students
2014 – today	edX course " <a href="#">Autonomous Mobile Robots</a> " over 100,000 registrations.
2013 – 2015	University of Zurich, "Fundamentals of Computer Vision and Image Processing"
2012 – 2015	ETH / UZH Co-Lecturer of the Masters course "Autonomous Mobile Robots"
2008 – 2010	ETH, Co-Lecturer of the Masters course "Autonomous Mobile Robots"
2006	EPFL, Teaching Assistant for the course on C++ Programming
2005	EPFL, Teaching Assistant for the course on C++ Programming



## Invited speaker (conferences, workshops, summer schools)

### 2023

1. [Embodied AI Conference](#), March 22-24, 2023 (**keynote speaker**) (virtual)

### 2022

2. [CORL'22 workshop on Learning to Adapt and Improve in the Real World](#), Dec. 15, 2022 (**keynote speaker**) (virtual)
3. [IEEE Int. Electronic Conf. on Computer and Knowledge Eng.](#), Mashhad, Iran, Nov. 18, 2022 (**keynote speaker**) (virtual)
4. [IROS'22 workshop on Agile Robotics: Perception, Learning, and Control](#), Oct. 27, 2022 (**keynote speaker**) (virtual)
5. [Latin American Robotics Symposium \(LARS\) 2022](#), Oct. 21, 2022 (**keynote speaker**) (virtual)
6. [CominLabs Days](#), Rennes, France, Oct. 11, 2022, virtual, (**keynote speaker**)
7. [Workshop on Embedded Optimization and Learning for Robotics](#), Freiburg, Oct. 11, 2022, (**keynote speaker**)
8. [Maker Faire Rome, Italy](#), Oct. 7, 2022, (**keynote speaker**)
9. [15th APCA Int. Conf. on Automatic Control and Soft Computing \(CONTROLO\)](#), July 8, 2022 (**keynote speaker**)
10. HUAWEI Machine Learning and Computer Vision workshop, Zurich, July 7, 2022 (**keynote speaker**)
11. [Neuromorphic Engineering Workshop Telluride Future Forum Technology](#), July 1, 2022, virtual (**keynote speaker**),
12. [MED'22 workshop on Active Vision Methods in Autonomous Navigation](#), Jun. 28, 2022 virtual (**keynote speaker**)
13. [RSS'22 Workshop on Learning from Diverse Online Data](#), Jun. 27, 2022 virtual (**keynote speaker**)
14. [Machine Learning Summer School \(BAYOYO\)](#), Istanbul, Turkey, Jun. 27, 2022, virtual (**keynote speaker**)
15. [CVPR'22 Workshop on Visual Odometry Based on Location Clues](#), Jun. 19, 2022 virtual (**keynote speaker**)
16. [Virtual and Augmented Reality Summer School \(IVAR\)](#), June 14, 2022 virtual (**keynote speaker**)
17. [International Congress on Photogrammetry and Remote Sensing \(ISPRS\)](#), Jun. 8, 2022 (**keynote speaker**)
18. [ICRA'22 workshop on Behaviour Priors in Reinforcement Learning for Robotics](#), May 27, 2022 (**keynote speaker**)
19. [ICRA'22 workshop on Aerial Robotics](#), May 23, 2022 (**keynote speaker**)
20. [Drone Show Korea](#), Feb. 25, 2022 (virtual) (**keynote speaker**)
21. [Robohub Podcast on Event cameras with Abate De Mey](#), Jan. 28, 2022. virtual

### 2021

22. [IEEE RSI 9 th International Conference on Robotics and Mechatronics, Nov. 2021](#), Iran, virtual (**keynote speaker**)
23. [2021 International Joint Conference on Robotics and Artificial Intelligence, Nov., 2021](#), China, virtual (**keynote speaker**)
24. [Conference on Robot Learning \(CORL\), November, 2021](#) (**keynote speaker**)
25. [IEEE International Symposium on Safety, Security, and Rescue Robotics \(SSRR\)](#), October 2021 (**plenary speaker**)
26. [21st Int. Conf. on Control, Automation and Systems \(ICCAS\)](#), October 2021 (**plenary speaker**)
27. [United Nations Environment Program, Drones for search and rescue](#), October 2021 (**keynote speaker**)
28. [House of Switzerland](#), Stuttgart (**keynote speaker**)
29. [ETH Workshop on AI in the Sciences and Engineering](#), Sep. 28, 2021 (**keynote speaker**)
30. [IEEE Int. Conference on Multisensor Fusion and Integration \(MFI\)](#), Karlsruhe, Sep. 2021 (**plenary speaker**)
31. Automatica, Munich, June 22, 2021 (**keynote speaker**)
32. CVPR'21 workshop on [Image Matching: Local Features and Beyond](#), June 25, 2021 (**keynote speaker**)
33. CVPR'21 workshop on [Egocentric Perception, Interaction and Computing](#), June 20, 2021 (**keynote speaker**)
34. CVPR'21 workshop on [Large Scale Computer Vision for Remote Sensing Imagery](#), June 19, 2021 (**keynote speaker**)
35. ICRA'21 workshop on ["Perception and Action in Dynamic Environments"](#), June 4, 2021, virtual (**keynote speaker**)
36. ICRA'21 workshop on ["On- and Near-sensor Vision Processing"](#), June 4, 2021, virtual (**keynote speaker**)
37. Workshop on Ethics of Humanitarian Drones, June 2, 2021, Geneva (**keynote speaker**)

38. ICRA'21 workshop on "[Opportunities and Challenges with Autonomous Racing](#)", May 31, 2021, virtual (**keynote speaker**)
39. ICRA'21 workshop on "[Resilient and Long-Term Autonomy for Aerial Robots](#)", May 31, 2021, virtual (**keynote speaker**)
40. ICRA'21 workshop on "[Robust Perception for Autonomous Field Robots](#)", May 31, 2021, virtual (**keynote speaker**)
41. Workshop on Ethics of Humanitarian Drones, March 23, 2021, virtual (**keynote speaker**)
42. Intel Neuromorphic Workshop, Feb. 09, 2021, virtual (**keynote speaker**)
43. 21st International Conference on Control, Automation and Systems (ICCAS 2021), (**plenary speaker**)
44. AIAA Session on AlphaPilot AIRR Autonomous Drone Race competition, Jan. 11, 2021, virtual (**plenary speaker**)

## 2020

45. RoboVis, Australia, November 25, 2020, virtual (**keynote speaker**)
46. Huawei smart camera workshop, November 20, 2020, virtual (**keynote speaker**)
47. Robotics Today Seminar Series, November 13, 2020, virtual (**keynote speaker**)
48. United Nations, Technology Development workshop, November 11, 2020, virtual (**keynote speaker**)
49. 25th International Humanitarian & Security Conference, October 2, 2020, Geneva (**keynote speaker**)
50. Brazilian Conference on Mechatronics, September 30, 2020, virtual (**keynote speaker**)
51. German Conference on Pattern Recognition (DAGM), September 28, 2020, virtual (**keynote speaker**)
52. Huawei Video Summit, September 10, 2020, virtual (**keynote speaker**)
53. Irish Machine Vision Conference, August 31, 2020, virtual (**keynote speaker**)
54. ECCV'20 Embedded Vision Workshop, August 28, 2020, virtual (**keynote speaker**)
55. ECCV'20 UAVision Workshop, August 28, 2020, virtual (**keynote speaker**)
56. ECCV'20 4D Vision, August 23, 2020, virtual (**keynote speaker**)
57. Dronitaly, July 16, 2020, virtual (**keynote speaker**)
58. ICRA'20 Workshop on Perception, Action, Learning, June 11, 2020, virtual (**keynote speaker**)
59. Computer Vision Summer School, Udine, June 29, 2020, virtual (**keynote speaker**)
60. Event-based Camera Workshop, June 16, 2020, virtual (**keynote speaker**)
61. CVPR'20 OmniVision Workshop, June 15, 2020, virtual (**keynote speaker**)
62. ICRA'20 Workshop on the Debates on the Future of Robotics Research, June 5, 2020, virtual (**keynote speaker**)
63. ICRA'20 Workshop on Unconventional Sensors in Robotics, June 4, 2020, virtual (**keynote speaker**)

## 2019

64. IROS'19 Workshop "Visual Inertial Navigation", November 8, 2019, (**keynote speaker**)
65. IROS'19 Workshop "Vision-based Drones", November 8, 2019, (**keynote speaker**)
66. IROS'19 Workshop "Towards Cognitive Vehicles", November 8, 2019 (**keynote speaker**)
67. International Micro Aerial Vehicle Conference, Madrid, October, 2019 (**keynote speaker**)
68. International Conference on Image Analysis and Processing, Trento, September, 2019. (**keynote speaker**)
69. Smart Maintenance Conference, Zurich, September, 2019. (**keynote speaker**)
70. Field and Service Robotics Conference, Tokyo, August, 2019. (**keynote speaker**)
71. International Computer Vision Summer School (ICVSS), Sicily, July, 2019. (**keynote speaker**)
72. International Conference on Advances in Robotics conference, Madras, July, 2019. (**keynote speaker**)
73. RSS Workshop on "Scene understanding for self-driving cars", Freiburg, June, 2019. (**keynote speaker**)
74. RSS Workshop on "Perception and Control for Fast and Agile Super-vehicles", Freiburg, June, 2019. (**keynote speaker**)
75. RSS Workshop on "Challenges in aerial physical interaction", Freiburg, June, 2019. (**keynote speaker**)
76. ICRA'19 Workshop "Learning in-the-Loop Systems in Autonomous Flight", 2019. (**keynote speaker**)
77. ICRA'19 Workshop "Reproducible Research in Robotics", Montreal, Canada, May, 2019. (**keynote speaker**)
78. ICRA19 Workshop "MATLAB and Simulink for Robotics Research", Montreal, Canada, May, 2019. (**keynote speaker**)
79. ICRA19 Workshop "The Future of Aerial Robotics", Montreal, Canada, May, 2019. (**keynote speaker**)
80. ICRA19 Workshop "Benchmarking of SLAM Algorithms", Montreal, Canada, May, 2019. (**keynote speaker**)
81. United Nations, expert group on New Trends and Technologies, Geneva, April, 2019. (**keynote speaker**)

## 2018

82. CNRS Journees National de la Robotique, Nov. 21, 2018 (**keynote speaker**)
83. Robotics Research in Switzerland, Kilometro Rosso, Bergamo, Nov. 13, 2018, Italy (**keynote speaker**)
84. IROS18 Workshop on Unconventional Sensing and Processing, Oct. 5, 2018 (**keynote speaker**)
85. IROS18 Workshop on Vision-based Drones: What's next? Oct. 5, 2018
86. INTEL NIS Workshop, Munich, Sep. 4-5, 2018 (**keynote speaker**)
87. 2<sup>nd</sup> International Symposium on Aerial Robotics, Jun 11-12, 2018, Philadelphia, USA (**keynote speaker**)
88. ISPRS18 TC II Symposium Towards Photogrammetry 2020, Italy, Riva del Garda, Jun. 4, 2018 (**plenary speaker**)
89. ICRA18 Workshop on The interplay between optimal estimation, Brisbane, May 25, 2018 (**keynote speaker**)
90. ICRA18 Workshop on Aerial Robotic Inspection and Maintenance, May 25, 2018 (**keynote speaker**)
91. ICRA18 Workshop on Human Robot Interaction with UAVs, Brisbane, May 21, 2018 (**keynote speaker**)
92. ICRA18 Workshop on Reproducible Research in Robotics, Brisbane, May 21, 2018 (**keynote speaker**)
93. IST Austria's Young Scientists Symposium, IST, Vienna, May 4, 2018 (**plenary speaker**)
94. SPIE conference, Orlando, April, 2018 (**keynote speaker**)

95. ERF18 Workshop on Aerial Robotics for Industrial Inspection, Tampere, Mar., 2018 (**keynote speaker**)
96. Winter Computer Vision Workshop, Prague, Feb. 2018, (**keynote speaker**)

## 2017

97. ICCV Workshop on UAV Vision, Venice, Italy, Oct. 2017, (**keynote speaker**)
98. ICCV Workshop on Visual Object Tracking Challenge, Venice, Italy, Oct. 2017, (**keynote speaker**)
99. ICCV Workshop, Role of Simulation in Computer Vision, Venice, Italy, Oct. 2017 (**keynote speaker**)
- 100.3DV 2017 conference, Qingdao, China, Oct. 2017, (**keynote speaker**)
- 101.IROS workshop on vision controlled UAVs, Vancouver, Canada, Sep. 2017, (**keynote speaker**)
- 102.Microsoft Research invited talk, Microsoft Research Headquarters, Seattle, USA, Sep. 2017
- 103.Amazon invited talk (Amazon headquarters), Seattle, USA, Sep. 2017
- 104.International Conference on UAV in Geomatics, Bonn, Germany, Sep. 2017 (**keynote speaker**)
- 105.European Conference on Mobile Robots, Paris, Sep. 2017 (**plenary speaker**)
- 106.Intel Network of Intelligent Systems Workshop, Aug. 2017 (**keynote speaker**)
- 107.Cooperative Dynamic Simultaneous Localization and Mapping, Zagreb, Croatia, Sep. 2017 (**keynote speaker**)
- 108.Workshop on Computer Vision in Vehicle Technology, CVPR'17, Honolulu, July, 2017 (**keynote speaker**)
- 109.BMVA Summer School, Lincoln, UK, June, 2017
- 110.Swiss Post Annual IT conference (700 people), Bern, Switzerland, 2017 (**keynote speaker**)
- 111.Workshop on Multi-Robot Perception-Driven Control and Planning, ICRA'17, Singapore, June, 2017 (**keynote speaker**)
- 112.Workshop on Reproducible Research in Robotics, ICRA'17, Singapore, June, 2017 (**keynote speaker**)
- 113.Neuromorphic Engineering Workshop, Capocaccia, Italy, Apr. 2017
- 114.European Robotics Forum, Edinburgh, UK, Mar. 2017
- 115.Mohammed bin al Zayed competition, Abu Dhabi, Emirate, Mar. 2017
- 116.Australian Robotic Vision Summer School, Canberra, March, 2017 (**keynote speaker**)

## 2016

- 117.NCCR Robotics Industry Day, Zurich, November, 2016 (**keynote speaker**)
- 118.IEEE IROS'16 Tutorial on Visual SLAM, Daejeon, South Korea, October, 2016 (**keynote speaker**)
- 119.IEEE Colombian Conference on Robotics and Automation, Bogota, September, 2016 (**keynote speaker**)
- 120.14<sup>th</sup> International Conference on Intelligent Systems, Shanghai, July, 2016 (**plenary speaker**)
- 121.20<sup>th</sup> Robocup Symposium, Leipzig, July 2016 (**keynote speaker**)
- 122.Machine Intelligence Summit, Berlin, June 2016 (**keynote speaker**)
- 123.SHERPA summer school, June, Trento, Italy 2016
- 124.Tutorial on Micro Aerial Vehicles, Int. Conference on Robotics and Automation, ICRA16, Stockholm
- 125.University of Sao Paulo, Brazilian Symposium on Robotics and Mechatronics, May, 2016 (**plenary speaker**)

## 2015

- 126.Dagstuhl School on Vision for Autonomous Vehicles, November, 2015
- 127.International Workshop on Software Engineering for Resilient Systems, Paris, September, 2015 (**keynote speaker**)
- 128.Int. Conference on Intelligent Robotics and Applications, Portsmouth, UK, August, 2015 (**plenary speaker**)
- 129.Armasuisse UAV workshop, Thun, July, 2015
- 130.IEEE Italy Section Summer School, Perugia, June, 2015.
- 131.Int. Workshop on "The problem of mobile sensors: setting future goals and indicators for SLAM", RSS'15, May, 2015
- 132.Innorobo, Workshop on "Towards Robust and Safe Autonomous Drones", Lyon, July, 2015. (**keynote speaker**)
- 133.International Workshop on "Scaling up active perception", ICRA'15, Seattle, May, 2015
- 134.International Workshop on Neuromorphic Sensing, ICRA'15, Seattle, May, 2015
- 135.International Workshop on Taxonomy of Interconnected Systems, ICRA'15, Seattle, May, 2015
- 136.Armasuisse Workshop on Multi-agent systems, Thun, May 2015.
- 137.Computer vision Winter workshop, Graz, February 2015 (**keynote speaker**)
- 138.Workshop on Future UAS Technologies, Thun, Switzerland, Jan. 2015

## 2014

- 139.Int. Summer School on Cooperation of Robots and Sensor Networks, TU Darmstadt, Sep. 2014 (**keynote speaker**)
- 140.3rd Int. Workshop on Visual Control of Mobile Robots (IROS'14), Chicago, Sep. 2014
- 141.Int. Workshop on Aerial Open Source Robotics (IROS'14), Chicago, Sep. 2014
- 142.Int. Workshop on Transducers for robot autonomous navigation, Benevento, Italy, Sep. 2014 (**keynote speaker**)
- 143.International Data Fusion and Big Data Workshop, Thun, ArmaSuisse, Switzerland, August 2014
- 144.3rd Workshop on Integration of Planning and Perception for MAVs (RSS'14), Berkley, July, 2014 (**keynote speaker**)
- 145.2<sup>nd</sup> International workshop on Multi-Unmanned Vehicle Systems (**keynote speaker**), Compiègne, France, July, 2014
- 146.12<sup>th</sup> Int. Workshop on Non-Classical Cameras, Camera Networks and Omnid. Vision (ICRA'14), Hong Kong, June, 2014.
- 147.International Workshop on Robotic Sensor Networks (**keynote speaker**), Berlin, April, 2014

## 2013

- 148.5th Workshop on Planning, Perception and Navigation for Intelligent Vehicles (IROS'13), (**keynote speaker**)
- 149.French National Robotics Days (Journées Nationales de la Recherche en Robotique), Annecy, Oct., 2013
- 150.4th JRC ECML Workshop on Unmanned Aerial Systems for Rapid Mapping, Geneva, September, 2013
- 151.Workshop on "Towards a Swiss Robotic Rescue Team" (**keynote speaker**), (ICRA'13), 2013

## 2012

- 152.TEDx Zurich, Oct. 25, 2012
- 153.AIROBOTS Summer School on Micro Aerial Vehicles, Zurich, July 2012.
- 154.Workshop on "Open problems and challenges in aerial robotics Europe", (RSS'12), (**keynote speaker**), 2012

## 2008 – 2011

- 155.International Mechanical Engineering Congress IMPULSO, (**keynote speaker**) Monterrey, November, 2011.
- 156.SFLY Summer School on Micro Aerial Vehicles, Zurich, July 2011
- 157.Workshop on continuous geo-positioning of individuals, organized by Armasuisse, Switzerland, 2010.
- 158.IEEE International Workshop on Safety, Security & Rescue Robotics (SSRR'10) (**keynote speaker**), 2010
- 159.Brazilian Symposium on Robotics and Mechatronics (SEMATRON'10) (**keynote speaker**), Sao Paulo, 2010.
- 160.Workshop on Omnidirectional Robot Vision (**keynote speaker**), held during ICRA'10, Alaska, May, 2010
- 161.Workshop on Communication, Control, and Perception for Teams of Small Robots, ICRA'10, May, 2010.
- 162.Workshop on Good Experimental Methodology and Benchmarking in Robotics Research, EURON, 2010.
- 163.International Conference on Cognitive Systems (CogSys'09), Zurich, Switzerland, January 2010.
- 164.South-African Conference on Pattern Recognition (PRASA'09) (**keynote speaker**), Cape Town, 2009.
- 165.South-African Conference on Robotics, Johannesburg (**keynote speaker**), November 9, 2009.
- 166.Swedish Workshop on Robotics, Vasteras, Sweden, September 8, 2009.
- 167.International Workshop on Visual Mapping and Navigation in Outdoor Environments, ICRA'09, 2009.
- 168.First International Workshop on Omnidirectional Robot Vision, November 4, 2008, Venice, Italy.

## Invited seminars

1. Johns Hopkins University, December 1, 2022. Virtual
2. European Space Agency, Nov. 24, 2022.(virtual)
3. Italian Institute of Technology, October 6, 2022. Virtual
4. General Motors Israel, June 7, 2022. Virtual.
5. UZH Foundation, May 20, 2022.
6. ETH EFCL seminar, Mar. 16, 2022.
7. CMU Tartan workshop, October 21, 2021, virtual
8. Harbin Institute of Technology, July, 2021, virtual
9. Huawei summit, June 25, 2021, virtual
10. University of Toronto, May 14, 2021, virtual
11. UC Berkeley, May 7, 2021, virtual
12. University of Pennsylvania, GRASP ON seminar series, April 23, 2021, virtual
13. EMPA, April 23, 2021, virtual
14. DSI Digital Society Initiative, Feb. 08, 2021, virtual
15. AMS invited talk, Austria, Jan. 26, 2021, virtual
16. DJI invited talk, Shenzhen, Jan. 11, 2021, virtual
17. University of Zaragoza, October 28, 2020, virtual
18. Universita' Politecnica delle Marche, April 15, 2020, virtual
19. Max Planck Institute, Tübingen, Bernstein Lectures, November 14, 2019
20. BOSCH AI seminar, Renningen, Sep. 5, 2019
21. Intel Madras, July 4, 2019
22. IIT Madras, July 2, 2019
23. Stanford University, May 17, 2019.
24. Nuro, Intel, Skydio, Aeye, May, 2019
25. UC Berkeley, May 6, 2019.
26. University of Maryland, October, 26, 2018
27. Khalifa University, Abu Dhabi, Sep. 17, 2018
28. MIT, Media Lab, virtual, July 10, 2018
29. Princeton University, April 16, 2018
30. University of Southern Denmark, April, 2018
31. Georgia Tech Atlanta, Sep. 2017
32. CMU Robotics Institute Seminar Series, February, 2017

33. Universidad Pontificia de Bogota, September, 2016.
34. USP Sao Paulo (inviter Prof. Dr. Marcelo Becker), May 2016
35. Qualcomm, Vienna, October. 2015
36. MIT, (inviter Andrea Censi) May, 2015
37. Indian Institute of Technology at New Delhi, Allahabad, and Kanpur (inviter SwissNex India), March 2015.
38. University of Zaragoza (inviter Prof. Jose Neira), Dec. 2014
39. University of Naples Federico II (inviter Prof. Bruno Siciliano), Sep, 2014
40. ETH Computer Vision Lab (inviter Prof. Luc Van Gool), August, 2014
41. Carnegie Mellon University (inviter Prof. Sanjiv Singh), July 2014.
42. Polytechnique of Torino (inviter Prof. Marcello Chiamberge), July 2014
43. Advanced Center for Aerospace Technologies and University of Seville (inviter Prof. Anibal Ollero), September 2013.
44. USC Viterbi School of Engineering, Los Angeles (inviter Prof. Gaurav Sukhatme), March 2012.
45. EPFL Lausanne, (inviter Prof. Dario Floreano and Prof. Auke Ijspeert), March, 2011.
46. University of Zurich, (inviter Prof. Rolf Pfeifer), February, 2011.
47. Invited talk at the „Einführungstag für Master-Studierende“ (inviter Rector of ETH Zurich), September 2010.
48. Dynamic maps seminar (inviters Prof. Marc Pollefeys), Dagstuhl, 2010.
49. GRASP Lab, University of Pennsylvania (inviters Prof. Kostas Daniilidis and Prof. Vijay Kumar, July, 2010
50. Italian National Center of Research (CNR), Bari, July, 2010.
51. NASA Jet Propulsion Laboratory (JPL), (inviter Dr. Larry Matthies), Pasadena, US, May, 2010.
52. University of California Los Angeles (UCLA), (inviter Prof. Stefano Soatto), Vision Lab, US, May, 2010
53. Caltech, NESS seminar series, (inviter Prof. Pietro Perona), US, May, 2010
54. University of Southern California (USC), (inviter Prof. Gaurav Sukhatme), Los Angeles, US, May, 2010.
55. Stanford University, Artificial Intelligence Lab, (inviter Prof. Oussama Khatib), US, May, 2010.
56. Willow Garage, Menlo Park, (inviter Dr. Kurt Konolige), US, May, 2010.
57. Technical University of Crete, Chania, (inviter Prof. Dimitrios Rovas) Greece, April, 2010.
58. Department of Information Engineering, (inviter Prof. Emanuele Menegatti), University of Padua, 2010.
59. Caltech, Computational Vision Lab (inviter Prof. Pietro Perona), Pasadena, CA, November 6, 2007.
60. Department of Information Processing and Electronics, (inviter Prof. Paolo Valigi) University of Perugia, 2007.
61. INRIA, Grenoble, (inviter Prof. Christian Laugier), Grenoble, France, January, 2007.
62. Swiss Federal Institute of Technology Lausanne (EPFL), (inviter Prof. Pascal Fua), December, 2005.

## Summer school organizer

- First summer school on “Autonomous micro aerial vehicles: design, perception, and control”, 2011, ETH Zurich

## Workshop organizer

1. [“4<sup>th</sup> Workshop on Event-based Vision”](#), CVPR’23, 2023
2. Autonomous Drone Racing competition and workshop, ICRA’23, May, 2023.
3. [“Learning for Agile Robotics”](#), CORL’22, Dec. 15, 2022
4. [“Agile Robotics: Perception, Learning, Planning, and Control”](#), IROS’22, Oct. 23-27, 2022
5. [“DodgeDrone Challenge”](#) ICRA’22, May 27, 2022.
6. [“Releasing Robots into the Wild: Simulations, Benchmarks, and Deployment”](#), ICRA’22, May 27, 2022.
7. [“Integrated Perception, Learning, and Control for Agile Super Vehicles”](#), IROS’21, October, 2021.
8. [“Perception and Action in Highly-Dynamic Environments”](#), ICRA’21, virtual, June 4, 2021
9. [“3<sup>rd</sup> Workshop on Event-based Vision”](#), CVPR’21, virtual, June 19, 2021
10. [“Machine Learning for Mobile Robot Navigation in the Wild”](#), AAAI’21, virtual, Mar. 22-24, 2021
11. [“Workshop on Perception, Learning, and Control for Autonomous Agile Vehicles”](#), IROS’20, Nov. 2-3, 2020
12. [“Workshop on Perception and Control for Fast and Agile Super-Vehicles”](#), RSS’20, Las Vegas, July 12, 2020
13. [“Computer Vision for UAVs”](#), ECCV, Glasgow, August 28. 2020
14. [“Challenges in Vision-based Drone Navigation”](#), IROS, Macau, Nov. 8, 2019
15. [“2<sup>nd</sup> International Workshop on event-based Vision and Smart Cameras”](#), CVPR, Long Beach, CA, June 17, 2019
16. [“3<sup>rd</sup> International Workshop on Computer Vision for UAVs”](#), CVPR, Long Beach, CA, June 16, 2019
17. “Vision-based Drones: What's next?”, IROS, Madrid, Oct. 2018
18. [“2<sup>nd</sup> International Workshop on Computer Vision for UAVs”](#), ECCV, Munich, Sep. 2018
19. “Computer Vision for UAVs”, ICCV, Venice, October, 2017
20. “Vision-based Agile Autonomous Navigation of UAVs”, IROS, Vancouver, Canada, Sep., 2017
21. [“1<sup>st</sup> International Workshop on Event-based Vision”](#), ICRA, Singapore, June 2, 2017
22. “Vision-based High Speed Autonomous Navigation of UAVs”, IROS, Daejeon, South Korea, October, 2016
23. “Vision-based Control and Navigation of Small, Light-Weight UAVs”, IROS, Hamburg, Germany, October, 2015.
24. [“Innovative Sensing for Robotics: Focus on Neuromorphic Sensors”](#), ICRA, Seattle, USA, May, 2015
25. “Computer Vision in Vehicle Technology with Special Session on Micro Aerial Vehicles”, ECCV, Zurich, Switzerland, 2014
26. “Omnidirectional Vision, Camera Networks and Non-Classical Cameras, ICRA, Hong Kong, China, May, 2014



27. "Vision-based Control and Navigation of Micro Helicopters in GPS-denied Environments", IROS, Tokyo, Japan, Oct., 2013
28. "Micro-UAV Perception and Control", ICRA, Shanghai, China, May, 2011

## Postdoc Supervision

### Current postdocs:

1. Marco Cannici, PhD at Poli Milano
2. Christian Pfeiffer PhD at EPFL

### Past postdocs and where they are now:

1. Robert Penicka, PhD with Martin Saska at TU Prague, now group leader at TU Prague
2. Sihao Sun, PhD with Coen de Visser and Q. Chu at TU Delft, now postdoc at TU Delft
3. Javier Hidalgo, PhD with Udo Frese at ESA and Uni Bremen, now Magic Leap Zurich
4. Dimche Kostadinov, PhD with Slava Voloshynovskiy at Uni Geneva, now at SONY AVS Zurich
5. Dario Brescianini, PhD with Raffaello D'Andrea at ETH, now at SONY AI Zurich
6. Jeffrey Delmerico, PhD with Jason Corso at Uni Michigan, now at Microsoft Research Zurich
7. Guillermo Gallego, PhD with Antony Yezzi at Georgia Tech, now Professor at TU Berlin
8. Peng Lu, PhD with Coen de Visser and Q. Chu at TU Delft, now Professor at Uni Hong Kong
9. Suseong Kim, PhD with Jin Kim at Seoul National University, now at Electronics and Telecom Research Institute (ETRI)
10. Manuel Werlberger, PhD with Thomas Pock at TU Graz, co-founder of Zurich Eye, now at Meta Zurich
11. Sergei Lupashin, PhD with Raffaello D'Andrea at ETH, founder of Fotokite, now at NVIDIA Zurich
12. Matia Pizzoli, PhD with Fiora Pirri at La Sapienza Uni Rome, co-founder of Zurich Eye, now at Meta Zurich
13. Andras Majdik, PhD at Uni Cluj-Napoca, now at Hungarian Inst. Of Computer Science and Control
14. Reza Sabzevari, PhD with Alessio del Bue at Italian Institute of Technology, now at BOSCH Hildesheim

## PhD student Supervision

### Current PhD students at my lab at the University of Zurich:

1. Daniel Gehrig
2. Mathias Gehrig
3. Manasi Muglikar
4. Yunlong Song
5. Giovanni Cioffi
6. Nico Messikommer
7. Angel Romero
8. Leonard Bauersfeld
9. Drew Hanover

### Current PhD students co-supervised at ZHAW:

10. Banafshe Bamdad, student of Alireza Darwishi
11. Fatemeh Mohammadi, student of Hans Wernher van de Venn
12. Maryam Rezaayati, student of Hans Wernher van de Venn

### Current PhD students co-supervised at Balgrist:

13. Jecklin Sascha, student of Philipp Fürnstahl

### Graduated PhD students, their PhD thesis reviewers, and where they are now:

1. 2022 – Elia Kaufmann. Reviewers: Angela Schoellig, Vijay Kumar, Wolfram Burgard, Sertac Karaman. Now at Skydio
2. 2021 – Philipp Foehn. Reviewers: Moritz Diehl, Luca Carlone, Roland Siegwart. Now at Skydio
3. 2021 – Antonio Loquercio. Reviewers: Pieter Abbeel, Angela Schoellig, Roland Siegwart. Now postdoc at UC Berkeley
4. 2020 – Zichao Zhang. Reviewers: Frank Dellaert, Michael Kaess, Timothy Barfoot. Now at Chinese Academy of Sciences
5. 2020 – Titus Cieslewski. Reviewers: Torsten Sattler, Marc Pollefeys. Now at Verity AG
6. 2019 – Henri Rebecq. Reviewers: Andrew Davison, Bernt Schiele, Tobi Delbruck. Now at Google Zurich
7. 2019 – Davide Falanga. Reviewers: Nathan Michael, Sami Haddadin, Roland Sigewart. Now at Skydio
8. 2018 – Matthias Faessler. Reviewers: Antonio Franchi, Anibal Ollero. Now at Verity AG
9. 2017 – Elias Mueggler. Reviewers: Tobi Delbruck, Kostas Daniilidis. Now at Meta Reality Labs
10. 2016 – Christian Forster. Reviewers: Stefan Leutenegger, Marc Pollefeys. Co-founder of Zurich Eye, now at Meta Zurich

### Graduated co-Supervised PhD students

- Frederike Duembgen at EPFL, student of Martin Vetterli
- During my postdoc at UPenn: Roy Anati. Student of Kostas Daniilidis, now at Google Mountain View
- During my postdoc at ETH Zurich:
  - Laurent Kneip, student of Roland Siegwart, now Prof. at Shanghai Tech
  - Markus Achtelik, student of Roland Siegwart, now CTO of AuTeron
  - Stephan Weiss, student of Roland Siegwart, now Prof. at Uni Klagenfurt

## Master and Bachelor Student Supervision

>200 students. The full list can be found at the bottom of this page: <http://rpg.ifi.uzh.ch/people.html>

## Membership networks

- Associate Faculty of the ETH AI Center (Since 2021)
- Core member of the UZH Digital Society Initiative (DSI) at the University of Zurich (since 2018)
- Core member UZH Space Hub (since 2020)
- Core member of the UZH Innovation Hub (since 2020)
- Core member of Intel Neuromorphic Research Community (since 2020)
- Core Member of NCCR (National Center of Competence in Research) Robotics and
- Former Associate Faculty of Wyss Zurich (2015-2016)
- Member of the IEEE Robotics and Automation Society (since 2010)

## Chair or Member of Professor Hiring Committees

1. 2023 – UZH Open Rank Professorship on AI for Cyber Physical Systems, **Chair of the committee**
2. 2023 – UZH Assistant Professorship in Genetics of Language, Evolutionary Biology and Environmental Studies
3. 2019 – UZH Assistant Professorship in Big Data Science
4. 2019 – UZH Assistant Professorship in AI and Machine Learning
5. 2019 – ETH Assistant Professorship in Robotics
6. 2019 – UZH Professorship committee for the PaP appointment of Prof. Jetzer
7. 2019 – UZH Professorship in Empirical Economics / Empirical Policy Analysis
8. 2016 – UZH Professorship on Child and Welfare Development (UNICEF)
9. 2016 – UZH Professor in Development Economics
10. 2014 – UZH Professor in Neuroeconomics

## Journal Associate Editor

- 2014 – 2018: Associate Editor for the IEEE Transactions on Robotics.

## Journal guest editor

1. 2019 – Journal of Field Robotics, special issue on “Future Challenges and Opportunities in Vision-based Drone Navigation”
2. 2018 – Journal of Field Robotics, special issue on “High-Speed Vision-Based Autonomous Navigation of UAVs”
3. 2018 – Frontiers Journal, special issue on "Neuromorphic Sensory Functions in Neuro-robotics and Bionics and the Underlying Biological Processes"
4. 2018 – Autonomous Robots journal, special issue on “Active Perception”
5. 2017 – Journal of Field Robotics, special issue on “High-Speed Vision-Based Autonomous Navigation of UAVs”
6. 2012 – Autonomous Robots journal, special issue on “Micro UAV, Perception and Control”

## Journal Advisory Board

2012 – Today – International Journal on Robotics Research, EiC: Antonio Bicchi

## IEEE Technical Committee on Robot Vision

2018 to 2021 - Chair of the IEEE Robotics and Automation Society Technical Committee on Robot Vision

## Conference services

- Local chair of CORL'18
- Demo Chair of ECCV'14
- Editor of ICRA'19-20-21
- Associate Editor of ICRA'12-17 and IROS'13-17
- Session Chair: ICRA'12-17 and IROS'13-18

## Project Proposal Reviewer

- ERC (European Research Council)
- SNSF (Swiss National Science Foundation)
- ETH Grants

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- Agence Nationale de la Recherche (French Research Council)
- Netherlands Organisation for Scientific Research (NWO)
- Veni Grants (Netherlands)
- Mexican Science Foundation

## Program Committee Member of International Conferences

- Robotics Science and Systems (RSS) (since 2010)
- IEEE Int. Conf. on Robotics and Automation (ICRA) (since 2006)
- IEEE/RJS Int. Conf. on Intelligent Robots and System (IROS) (since 2007)
- International Conference on Computer Vision (ICCV) (Since 2009)
- European Conference on Computer Vision (ECCV) (Since 2009)
- International Conference on Computer Vision and Pattern Recognition (since 2011)
- International Symposium of Robotics Research (ISRR'09)
- European Conference on Computer Vision (since 2011)
- International Conference on Computer Vision and Pattern Recognition (CVPR) (since 2011)
- AAAI Conference on Artificial Intelligence (since 2011)
- 8th Int. IFAC Symposium on Robot Control (SYROCO'06)
- IEEE Conf. on Automation Science and Engineering (CASE'07)
- Int. Conf. on Field and Service Robotics (FSR'07)
- German Workshop on Robotics (GWR'09)
- International Conference on Unmanned Aerial Vehicles (UAV'10)

## Journal Reviewer

- IEEE Transactions of Robotics (T-RO) (since 2008)
- IEEE Transactions of Pattern Analysis and Machine Intelligence (TPAMI) (since 2011)
- Autonomous Robots (AURO) (since 2011)
- Journal of Field Robotics (JFR) (since 2009)
- International Journal of Robotics Research (IJRR) (since 2009)
- Robotics and Automation Magazine (RAS) (since 2008)
- International Journal of Computer Vision (IJCV) (since 2010)
- Journal of Image and Vision Computing (IMAVIS'10)
- Robotics and Autonomous Systems, Elsevier (since 2009)
- EURASIP Journal on Image and Video Processing (since 2009)
- Computer Vision and Image Understanding (since 2008)
- IET Computer Vision (IET'08)
- IEEE Transactions on Instrumentation and Measurement (2008)
- Elsevier, Pattern Recognition Letters (since 2008)

## Reviewer and Examiner of PhD Theses

1. 2022 – **ETH Zurich**, Marcel Geppert, (student of Marc Pollefeys)
2. 2023 – **TU Munich**, Lukas Stumberg, (student of Daniel Cremers)
3. 2023 – **Aarso University**, Xuan Huy Pham, (student of Erdal Kayakan)
4. 2022 – **University of Toronto**, Jason Rebello, (student of Steven Waslander)
5. 2022 – **UPENN**, Wenxin Liu, (student of Vijay Kumar and Kostas Daniilidis)
6. 2021 – **Shanghai Tech**, Xin Peng, (student of Laurent Kneip)
7. 2021 – **EPFL**, Frederike Duembgen (student of Martin Vetterli)
8. 2021 – **ETH Zurich**, Peidong Liu (student of Marc Pollefeys)
9. 2021 – **NTU Singapore**, Wang Qinyi
10. 2020 – **TU Delft**, Sihao Sun (Student of Coen De Visser)
11. 2019 – **ETH Zurich**, Daniele Palossi (student of Luca Benini)
12. 2019 – **ETH Zurich**, Simon Lynen (student of Roland Siegwart)
13. 2018 – **ETH Zurich**, Federico Camposeco (student of Marc Pollefeys)
14. 2018 – **ETH Zurich**, Lorenz Meier (student of Marc Pollefeys)
15. 2017 – **EPFL** Lausanne, Steven Roelofsen (student of Alcherio Martinoli)
16. 2017 – **ETH Zurich**, Lorenz Meier, (student of Marc Pollefeys)
17. 2016 – **INRIA Marseille**, Stefano Mafrica (student of Franck Ruffier)
18. 2016 – **UPENN**, Roy Anati, (student of Kostas Daniilidis)
19. 2016 – **University of Perugia**, Gabriele Costante (student of Paolo Valigi)
20. 2016 – **ETH Zurich**, Olivier Saurer (student of Marc Pollefeys)

21. 2016 – **EPFL Lausanne**, Maja Varga (student of Dario Floreano)
22. 2015 – **University of Cape Town**, Natasha Govender
23. 2015 – **ETH Zurich**, Andreas Nussberger (student of Luc Van Gool)
24. 2015 – **University of Halmstad**, Sweden, (student of Roland Philippsen)
25. 2015 – **USP**, Univ. of Sao Paulo, Brasil, Raphael Coronel (student of Marcelo Becker)
26. 2014 – **University of Zaragoza**, Yasir Latif (student of Jose Neira)
27. 2014 – **UPENN**, Shaojie Shen, (student of Vijay Kumar)
28. 2014 – **Freie Universitaet Berlin**, Sven Oluf (student of Markus Vincze and Raul Rojas)
29. 2014 – **University of Coimbra**, Michel Antunes, (student of Joao Barreto)
30. 2014 – **INRIA**, Grenoble, Chiara Troiani (student of Christian Laugier)
31. 2014 – **Max Planck Institute**, Volker Grabe (student of Heinrich Bulthoff and Paolo Robuffo Giordano)
32. 2013 – **EPFL Lausanne**, Adrien Briod (student of Dario Floreano)
33. 2013 – **EPFL Lausanne**, Amanda Prorok, (student of Alcherio Martinoli)
34. 2013 – **Polytechnic of Milan**, Ehsan Asadi (Student of Carlo Bottasso)
35. 2012 – **ETH Zurich**, Laurent Kneip (student of Roland Siegwart)
36. 2012 – **ETH Zurich**, Sergei Lupashin (student of Raff D'Andrea)

## Attraction of Professors for research stays

Since my appointment at UZH, my research has attracted several professors world top institutions, who stayed from weeks to months:

- **University of York**: Prof. Kosta Derpanis, Summer 2018
- **Shanghai Tech**: Prof. Laurent Kneip, Summer 2018
- **CNRS/INRIA Toulouse**: Prof. Antonio Franchi, Summer 2017
- **Stanford University**: Prof. Mac Schwager, Summer 2017
- **University of Parma**: Prof. Stefano Ghidoni, Fall 2016.
- **UCLA**, Prof. Stefano Soatto, Summer 2014.

## Attraction of International Visiting Scientists

Since my appointment at UZH, my research has attracted Postdocs, PhD students, and undergraduate students from international and world top institutions:

- **Shanghai Tech**: Ling Gao, student of Laurent Kneip, 2023
- **Uni Bologna**: Lorenzo Lamberti, student of Luca Benini, 2023
- **Italian Institute of Technology**: Giuseppe l'Erario, student of Daniele Pucci, 2023
- **University of Seville**: Julio Lopez Paneque, student of Anibal Ollero, from Jan. to July 2021
- **University of Michigan**: Drew Hanover, Feb. to August 2021.
- **TU Munich**: Simon Klenk, student of Daniel Cremers, Apr to Oct. 2021
- **Shanghai Tech**: Xin Peng, student of Laurent Kneip, 2021
- **Sant'Anna of Pisa**: Oct. 2020 to Apr. 2021, Mario Bonsembiante, Lorenzo Ferrini, Prof. Davide Bacciu
- **University of Bologna**: Roberto Tazzari, student of Lorenzo Marconi, Nov. 2019 to March 2020.
- **Tohoku University**: Yuto Suebe, student of Kazuya Yoshida, Nov. 2019 to March 2020.
- **University of British Columbia**: Rika Sugimoto, June to Sep, 2019
- **University of Seville**: Dr. Francisco Perez, Anibal Ollero's student, Sep. 2018 to Jan. 2019
- **Monash University**: Timo Stroffegen, Tom Drummond's student, Jun. 2018 to Dec. 2018
- **Australian National University**: Cedric Scheerlinck, Robert Mahony's student, Sep 2018 to Sep. 2019
- **Universida Politecnica de Madrid**: Ana Maqueda, March to Sep. 2017, Prof. Carlos R. Del Blanco
- **Australian National University (ANU)**: Yi Zhou, student of Laurent Kneip and Hongdong Li, Sep. 2017 to Mar. 2018.
- **University of Malaga**: Ruben Gomez, Sep. 2016 to March 2017, Prof. Javier Gonzalez-Jimenez
- **Toyota Research Institute (TRI)**: Dr. Naveen Kuppurwami, visiting postdoc, Jan. 2016 to June 2017.
- **University of Cape Town**: Ms Ra'eesah Mangera is currently visiting Msc student in my lab. 2014
- **University of Genova**: Damiano Verda, visiting PhD student, visiting PhD student from Jan. to Sep. 2013.
- **University of Sao Paulo in Brazil**: Ms Nathaly Gasparin is currently a visiting Bsc student in my lab. 2013
- **Beijing Institute of Technology**: Yanhua Jiang spent 1 year as visiting PhD student in my lab ifrom 2012 to 2013.
- **Carnegie Mellon University (CMU)**: Kumar Shaurya Shankar, PhD student of Nathan Michael
- **Italian Institute of Technology (IIT)**: Reza Sabzevari, visiting PhD student in summer 2013.
- **INRIA**: Chiara Troiani spent 9 months as visiting PhD student in my lab in 2013.
- **Max Planck**: Volker Grabe spent 1 year as visiting PhD student in my lab from 2012 to 2013.
- **Carnegie Mellon University**: Xin Yu and Sahuria Shankar Kumar were visiting Msc students in my lab in 2014
- **Caltech/MIT**: Dr. Andrea Censi spent 6 months visiting my lab from 2012 to 2013.

## International Robot Competitions

2022	<b>1<sup>st</sup> AI vs Human Drone race</b> – Self organized
2019	<b>AlphaPilot Autonomous Drone Racing competition</b> (2 <sup>nd</sup> place winner)
2015 - 2018	<b>DARPA FLA</b> (Fast Lightweight Autonomy)
2017	<b>IROS Autonomous Drone Race</b> (2 <sup>nd</sup> place winner)
2015 - 2016	<b>MBZIRC</b> (Mohamed Bin Zayed International Robotics Challenge)
2014	<b>KUKA Innovation Award</b> (Winner, 20k EUR)
2009	<b>EMAV: European Micro Aerial Vehicle Competition</b> , (2 <sup>nd</sup> place winner): <a href="#">LINK</a>
2006	<b>ELROB: First European Land Robot Trial</b> : <a href="#">LINK</a>

## Public Exhibitions with live flying-robot demos

- **NCCR Industry Day 2022**, Lausanne. Nov. 4-5, 2022, 10,000 visitors
- **CIOMove**, Duebendorf, July 17, 2022, 100 visitors
- **Swiss Drone Days**, Duebendorf, June 10-12, 2022, 1000 visitors
- **NCCR Industry Day 2021**, Zurich. Nov. 2, 2021, 2000 visitors
- **NCCR Demo Day 2021**, Duebendorf, Nov. 1, 2021, 100 visitors
- **Scientifica 2021**, Duebendorf, Sep. 3, 2021: 600 visitors
- **ETH Robotics Sum. School 2021**, Duebendorf, Jul. 4, 2022: 70 visitors
- **NCCR Industry Day 2019**, Lausanne, Nov. 2019, 200 visitors
- **NCCR Industry Day 2018**, Lausanne, Nov. 2018, 200 visitors
- **CORL'18 conference**, Zurich 29-31 Oct. 2018, 400 visitors
- **100 Ways of Thinking**, Zurich, Kunsthalle, Sep. 2018, 500 visitors
- **ARCHE** search and rescue demo, Bern, July 5, 2018, 300 visitors
- **Inauguration of the Duebendorf InnoPark**, March 2, 2018, 300 visitors
- **NCCR Industry Day 2017**, Lausanne, Nov. 2017, 500 visitors
- **FSR'17 conference**, Zurich, Switzerland, Sep. 2017, 200 visitors
- **Scientifica 2017**, 01-03 Sep. 2017, 20,000 visitors
- **Achilles 2017**: search and rescue demonstration, Epeisses, Geneva, May, 2017, 260 visitors
- **NCCR Industry Day 2016**, Lausanne, Nov. 2016, 500 visitors
- **SSRR'16 Conference**, Oct. 2016, 100 visitors
- **NCCR Industry Day 2015**, Nov. 2015, 500 visitors
- **Scientifica 2015**, Zurich, Sep. 2015, 20,000 visitors
- **IROS'15**, Hamburg, 02.10.2015, 150 visitors
- **ICRA'15**, Seattle, 27.06.2015, 150 visitors
- **SwissCore 2015**, Brussels, 12.05.2015, 100 visitors
- **CeBIT 2015 Expo**, Hannover, 16-20.03.2015, 30,000 visitors
- **AUTOMATICA 2014**, Munich, 3.-6.06.2014, 31,000 visitors [ [Link](#) ] [ [Video](#) ]
- **TunZurich 2013**, Zurich, 23-25 October, 2013, 1,000 visitors
- **Scientifica 2013**, Zurich, 31-01 September, 20,000 visitors, 2013
- **Robotic Festival 2013** Lausanne, EPFL, 20 April, 2013, 10,000 visitors
- **Robots on Tour 2013**, Zurich, 09 March, 2013, 4,000 visitors



## Media Coverage

My research has been featured in wider media, including **The New York Times**, **The Economist**, **Forbes**, **BBC News**, **Discovery Channel**, **La Repubblica**, **Neue Zürcher Zeitung** and in technology-focused media, such as **IEEE Spectrum**, **MIT Technology Review**, **Tech Crunch**, **Wired**, **The Verge**.

### Select list of recent coverage:

#### Recent TV Video reports:

- 11.11.2022 – **NZZ Format**, NZZ Format reports on our autonomous drone technology: [ [Link](#) ]
- 07.11.2022 – **SRF Tagesschau**, Swiss Robotics Days Lausanne: [ [Youtube \[DE\]](#) , [Youtube \[IT\]](#) , [SRF \[DE\]](#) [RSI \[IT\]](#) ]
- 13.07.2022 – **RAI-1 - SuperQuark**, A reportage on the Italian national TV, Video: [ [Link](#) ]
- 20.03.2020 – **SRF and 3Sat**, This documentary (German only) demonstrates our research on how autonomous drones can be used for search and rescue. (video starts at time 15:50) [ [Link](#) ]

#### Recent newspaper coverage:

28.1.2022 – **The Economist**, Our research on event cameras: [ [Link](#) ]



26.10.2021 – **Forbes**, Learning high-speed flight in the wild: [ [Link](#) ]

23.07.2021 – **Forbes**, AI-controlled drone racer beats human pilots for the first time: [ [Link](#) ]



09.01.2020 – **New York Times** – "A drone from the University of Zurich is an engineering and technical marvel..." [ [Link](#) ]



13.08.2019 – **BBC News**, Drones are able to change their shape while flying [ [Link](#) ]

29.05.2019 – **BBC**, Tech gives drone the ability to avoid mid-air crashes [ [Link](#) ]

21.04.2015 – **BBC**, "Drones Under Control" [ [Link](#) ]



16.05.2019 – **La Repubblica**, Interview with Davide Scaramuzza [ [Link](#) ]

14.12.2018 – **La Repubblica**, Droni con 'ali pieghevoli' per passare ovunque [ [Link](#) ]

14.02.2018 – **La Repubblica**, Tra alberi e palazzi ora il drone fa lo slalom [ [Link](#) ]



27.07.2019 – **Neue Zürcher Zeitung**, "In der Forschung zu autonom fliegenden Drohnen spielt die Uni Zurich weltweit an [ [Link](#) ]

30.08.2018 – **Neue Zürcher Zeitung**, "Wie Robotikprofessor Scaramuzza Erdbebenopfern mit Drohnen helfen will [ [Link](#) ]

24.01.2018 – **Neue Zürcher Zeitung**, "So kommen Drohnen sicher durch die Stadt" [ [Link](#) ]



07.07.2022 – **IEEE Spectrum**, IEEE Spectrum reports on the world's first AI vs. Human Drone Race organized by us: [ [Link](#) ]

08.10.2021 – **IEEE Spectrum**, Autonomous racing drones dodge through forests at 40 kph: [ [Link](#) ]

09.02.2021 – **IEEE Spectrum**, Quadrotor flight despite rotor failure with onboard sensors: [ [Link](#) ]

08.10.2020 – **IEEE Spectrum**, AI-Powered Drone Learns Extreme Acrobatics: [ [Link](#) ]

04.06.2019 – **IEEE Spectrum**, To Fly Solo, Racing Drones Have a Need for AI Speed Training [ [Link](#) ]

13.05.2019 – **IEEE Spectrum**, "Event Camera Helps Drone Dodge Thrown Objects" [ [Link](#) ]

25.01.2018 – **IEEE Spectrum**, "AI-Powered Drone Mimics Cars and Bikes to Navigate Through City Streets" [ [Link](#) ]



09.12.2016 – **MIT Technology Review**, "This Quadcopter Flies Aggressively Through Narrow Gaps" [ [Link](#) ]

25.07.2022 – **MIT Technology Review**, Interview on AI vs human world champions in Gran Turismo: [ [Link](#) ]



27.06.2018 – **Wired**, Drones Just Learned to Fly Solo, Which Means Pro Racers May Soon Meet Their Match [ [Link](#) ]

11.02.2016 – **Wired**, "This drone uses AI to find its way through a forest" [ [Link](#) ]

## Media Coverage – Full list

### 2022

- 09.12.2022 – **IEEE Spectrum**, The 10 year anniversary of our group is featured in IEEE Spectrum Video Friday: [ [Link](#) ]
- 01.12.2022 – **BUG.hr**, Croatian PC magazine BUG ranks D. Scaramuzza among 12 most important roboticists: [ [Link](#) ]
- 28.11.2022 – **Hackaday**, Our drone race against the worlds best drone pilot is featured in Hackaday: [ [Link](#) ]
- 23.11.2022 – **EE Times**, The electronics industry magazing EE Times reports on event-cameras: [ [Link](#) ]
- 21.11.2022 – **Haaretz**, Elbit Systems lists my lab as a pioneer on drones flying in complex environments using AI: [ [Link](#) ]
- 11.11.2022 – **NZZ Format**, NZZ Format reports on our autonomous drone technology: [ [Link](#) ]
- 07.11.2022 – **SRF Tagesschau**, Swiss Robotics Days Lausanne: [ [Youtube \[DE\]](#) , [Youtube \[IT\]](#) , [SRF \[DE\]](#) [RSI \[IT\]](#) ]
- 21.10.2022 – **UZH Space Hub**, UZH Space Hub reports on the parabolic flight campain in which RPG participated: [ [Link](#) ]
- 21.10.2022 – **AI Hub**, AI Hub reports on our work on training efficient controllers via analytic policy gradient: [ [Link](#) ]
- 12.10.2022 – **Tagblatt, Luzerner Zeitung**, Parabolic flight campaign in which my lab participated: [ [Link](#) , [Link](#) ]
- 12.10.2022 – **Business Insider**, Davide Scaramuzza provides an expert opinion on the Tesla Optimus Bot: [ [Link](#) ]
- 30.08.2022 – **WeWolver**, Our simulator Flightmare is featured: [ [Link](#) ]
- 15.08.2022 – **Electronics Weekly**, Electronics Weekly features our work on agile flight in cluttered environments: [ [Link](#) ]
- 31.07.2022 – **ZDF German TV**, Leonard Bauersfeld and Elia Kaufmann on ZDFs talk about drones: [ [Link](#) ]
- 27.07.2022 – **CIO move**, Our research on agile flights is featured in CIO move: [ [Link](#) ]
- 25.07.2022 – **MIT Technology Review**, interview on Sony AI that beat the world champions in Gran Turismo: [ [Link](#) ]
- 19.07.2022 – **Terninrete**, Our AI drones are part of RAI1 SuperQuark TV program: [ [Link](#) ]
- 17.07.2022 – **IEEE Spectrum**, Our work on minimum-time trajectory planning in Video Friday: [ [Link](#) ]
- 13.07.2022 – **RAI-1 - SuperQuark**, A reportage on the Italian national TV, Video: [ [Link](#) ]
- 13.07.2022 – **Planet Storyline**, Our open software and open hardware platform Agilicious: [ [Link](#) ]
- 08.07.2022 – **Emmett**, Our autonomous drones in the german communication and networking platform Emmett: [ [Link](#) ]
- 08.07.2022 – **Englisch & French News aggregators** report on the world's first AI vs. Human Drone Race: [ [Link](#) , [Link](#) ]
- 07.07.2022 – **IEEE Spectrum**, IEEE Spectrum reports on the world's first AI vs. Human Drone Race: [ [Link](#) ]
- 05.07.2022 – **Brazilian News**, Our open-source software and hardware platform Agilicious: [ [Link](#) ]
- 30.06.2022 – **Higgs**, Do we need to worry about the usage of Swiss drone technology in warzones?: [ [Link](#) ]
- 29.06.2022 – **Yahoo Finances & Mundo Conectado**, Our recent Science Robotics paper: [ [Link](#) , [Link](#) ]
- 28.06.2022 – **IEEE Spectrum**, Our work on frame interpolation with event cameras in Video Friday: [ [Link](#) ]
- 25.06.2022 – **SWI swissinfo.ch**, Usage of Swiss drone technology in warzones?: [ [German](#) , [English](#) , [Italian](#) , [Chinese](#) ]
- 18.05.2022 – **UK Institution of Mechanical Engineers**, Summary of our work, from drones to event cameras: [ [Link](#) ]
- 17.05.2022 – **News.ch**, Our autonomous drone racing at the Scientifica 2022: [ [Link](#) ]
- 11.05.2022 – **IEEE Spectrum**, Our work on time-optimal online replanning for agile flight in Video Friday: [ [Link](#) ]
- 05.05.2022 – **UZH News**, UZH lists AI racing-drones as a key finding of 2021: [ [Link](#) ] (starts at 26:00)
- 19.03.2022 – **UAS News**, UAS News reports on new Skydio hires from RPG: [ [Link](#) ]
- 15.03.2022 – **IEEE Spectrum**, Our work on learning control for agile quadcopter flight in Video Friday: [ [Link](#) ]
- 14.03.2022 – **From our lab to Skydio**, Skydio announces that it will be hiring some of our former PhD students. [ [Link](#) ]
- 10.03.2022 – **Interview with RoboHub**, Davide Scaramuzza talks about event cameras: [ [Article](#) , [Video](#) ]
- 09.03.2022 – **IEEE Spectrum**, Our obstacle-aware minimum-time planning for quadcopters in Video Friday: [ [Link](#) ]
- 02.03.2022 – **IEEE Spectrum**, Nonlinear MPC for quadrotor fault-tolerant control in Video Friday: [ [Link](#) ]
- 27.02.2022 – **Independent Turkey**, Our work on drones is featured in Independent Turkey: [ [Link](#) ]
- 16.02.2022 – **IEEE Spectrum**, Our work on event guided depth sensing in Video Friday: [ [Link](#) ]
- 15.2.2022 – **Image Sensors World**, Our work on event guided depth sensing is featured in Image Sensors World : [ [Link](#) ]
- 10.2.2022 – **Kanton Zurich**, Die Schweizer Hochburg der Robotik : [ [Link](#) ]
- 04.02.2022 – **Internazionale**, Article about our research on event cameras: [ [Link](#) ]
- 28.01.2022 – **The Economist**, Our research on event cameras featured in The Economist : [ [Link](#) ]
- 10.01.2022 – **UZH News**, RPG research makes it to the top 10 UZH news of 2021: [ [Link](#) ]

### 2021

- 08.11.2021 – **Die Redaktion**, Drohnen, Sensoren und Schwerelosigkeit: Hightech-Forschung in Dübendorf : [ [Link](#) ]
- 26.10.2021 – **Forbes**, This AI drone can speed through complex environments thanks to new virtual training : [ [Link](#) ]
- 20.10.2021 – **United Nations Environment Program**, D. Scaramuzza talks about drones in disaster management [ [Link](#) ]
- 20.10.2021 – **ETH AI Center**, D. Scaramuzza's talk at ETH Science and Engineering Workshop : [ [Link](#) ]
- 15.10.2021 – **House of Switzerland**, D. Scaramuzza talks about the future of aerial robotics: [ [Main event](#) ] , [ [Video](#) ]
- 10.10.2021 – **LA1 (Swiss Italian TV)**, D. Scaramuzza talks about high-Speed Drones for the Good: [ [Link](#) ]
- 11.10.2021 – **Metro UK**, "Artificial intelligence means drones can dodge through forests at 25mph" [ [Link](#) ]
- 08.10.2021 – **Futura-Sci1ences**, "Ces drones de compétition peuvent voler entre les branches dans une forêt" [ [Link](#) ]
- 08.10.2021 – **IEEE Spectrum**, Autonomous racing drones dodge through forests at 40 kph: [ [Link](#) ]
- 08.10.2021 – **Gazeta.Ru**, "Russian News coverage of our Science Robotics paper" [ [Link](#) ]
- 08.10.2021 – **Focus Online**, "Geschulte Drohnen sausen ins Unbekannte" [ [Link](#) ]
- 07.10.2021 – **Science Daily**, "Flying high-speed drones into the unknown with AI" [ [Link](#) ]
- 07.10.2021 – **Tech Xplore**, "Flying high-speed drones into the unknown with AI" [ [Link](#) ]
- 04.10.2021 – **Terni In Rete**, D. Scaramuzza il professore ternano che studia l'utilizzo dei droni autonomi [ [Link](#) ]
- 04.10.2021 – **Fierce Electronics**, D. Scaramuzza talks about Intel Loihi 2 research chip [ [Link](#) ]

- 26.09.2021 – **IEEE Spectrum Video Friday**, Nonlinear MPC for quadrotors: [ [Link](#) ]
- 26.09.2021 – **IEEE Spectrum Video Friday**, Autonomous drone racing by Philipp Foehn: [ [Link](#) ]
- 13.09.2021 – **Pupil Labs**, Human-Piloted Drone Racing: Visual Processing and Control: [ [Link](#) ]
- 18.08.2021 – **Corriere della Sera**, "I droni a guida autonoma sono più veloci di quelli pilotati" [ [Link](#) ]
- 17.08.2021 – **Robohub**, Davide Scaramuzza talks about his journey: [ [Link](#) ], [ [Video](#) ]
- 06.08.2021 – **CARLA Release**, Our contribution to the CARLA optical flow camera: [ [Link](#) ]
- 30.07.2021 – **Deutschlandfunk**, "Autonome Drohne fliegt schneller als Profi-Piloten – Interview Philipp Föhn" [ [Link](#) ]
- 26.07.2021 – **Engadget**, "Autonomous quadrotor beats two human pilots in a drone race" [ [Link](#) ]
- 26.07.2021 – **El Condencial**, "La inteligencia artificial vuelve a ganarnos, esta vez como piloto aéreo" [ [Link](#) ]
- 23.07.2021 – **Forbes**, "AI-Controlled Drone Racer Has Beaten Human Pilots For The First Time" [ [Link](#) ]
- 22.07.2021 – **Gizmodo**, "Autonomous Drone Just Beat a Professional Racing Pilot for the First Time" [ [Link](#) ]
- 22.07.2021 – **Interesting Engineering**, "New Algorithm Flies Drones, Beats Pace Set by Human Pilots" [ [Link](#) ]
- 22.07.2021 – **Robohub**, "New algorithm flies drones faster than human racing pilots" [ [Link](#) ]
- 22.07.2021 – **Tencent News**, "科学家研发新无人机算法 成功战胜2位世界级无人机驾驶员" [ [Link](#) ]
- 21.07.2021 – **Science Mag**, "New algorithm flies drones faster than human racing pilots" [ [Link](#) ]
- 21.07.2021 – **CT**, "Autonome Drohne am schnellsten" [ [Link](#) ]
- 21.07.2021 – **Science daily**, "New algorithm flies drones faster than human racing pilots can" [ [Link](#) ]
- 21.07.2021 – **New Atlas**, "Autonomous racing drone claims landmark victory against human pilots" [ [Link](#) ]
- 21.07.2021 – **20 Minuten**, "Computergesteuerte Drohne schlägt menschlichen Drohnenpilot" [ [Link](#) ]
- 21.07.2021 – **Swissinfo**, "Un algorithme manie un drone mieux que des pilotes professionnels" [ [Link](#) ]
- 21.07.2021 – **Engineering and Technology**, "Drone flight algorithm beats all human pilots in test race" [ [Link](#) ]
- 04.07.2021 – **IEEE Spectrum**, Our new drone testing arena is featured in IEEE Spectrum Video Friday: [ [Link](#) ]
- 22.06.2021 – **IEEE Spectrum Video Friday**, Davide Scaramuzza's talk at on Autonomous Racing: [ [Link](#) ]
- 27.05.2021 – **Tech Briefs**, Navigation Algorithm Enables Drones to Learn Acrobatic Maneuvers: [ [Link](#) ]
- 18.05.2021 – **Aminer**, Davide Scaramuzza is listed among the 100 most influential robotics scholar by Aminer: [ [Link](#) ]
- 07.05.2021 – **IEEE Spectrum Video Friday**, Davide Scaramuzza's talk at GRASP On Robotics seminar series: [ [Link](#) ]
- 26.04.2021 – **SwissInfo**, RPG research inspired Ingenuity's flight on Mars: [ [English](#) ], [ [Italian](#) ]
- 09.04.2021 – **SwissInfo**, Humans on Mars: possible, or a pipe dream? [ [Link](#) ]
- 19.03.2021 – **IEEE Spectrum Video Friday**, DodgeDrone challenge on perception and action: [ [Link](#) ]
- 01.03.2021 – **Tech Briefs**, Keeping Drones Flying When a Motor Fails: [ [Link](#) ]
- 12.02.2021 – **IEEE Spectrum**, Our work on data-driven MPC for quadrotors is on IEEE Spectrum Video Friday: [ [Link](#) ]
- 09.02.2021 – **IEEE Spectrum**, Autonomous quadrotor flight despite rotor failure with onboard vision sensors [ [Link](#) ]
- 01.02.2021 – **Tecnelab**, Davide Scaramuzza is interviewed about the future of drones: [ [Link](#) ] (in Italian)
- 21.01.2021 – **Aerospace and Defense**, Keeping Drones Flying When a Motor Fails: [ [Link](#) ]
- 14.01.2021 – **Robohub**, How to keep drones flying when a motor fails: [ [Link](#) ]
- 14.01.2021 – **UZH Space Hub**, Davide Scaramuzza is interviewed about our new Flying Arena: [ [Video](#) ]
- 13.01.2021 – **SwissInfo**, How to keep drones flying when a motor fails: [ [Link](#) ] (in German)
- 13.01.2021 – **ScienceDaily**, How to keep drones flying when a motor fails: [ [Link](#) ]
- 13.01.2021 – **Science Magazine**, How to keep drones flying when a motor fails: [ [Link](#) ]
- 13.01.2021 – **Computerworld**, How to keep drones flying when a motor fails: [ [Link](#) ] (in German)
- 13.01.2021 – **Blick**, How to keep drones flying when a motor fails: [ [Link](#) ] (in German)

## 2020

- 11.12.2020 - **NCCR Robotics**, Video of the article published by SwissInfo on November 2020: [ [Video](#) ]
- 28.11.2020 - **SwissInfo**, Swiss drones to the rescue! Davide Scaramuzza is interviewed about autonomous drones for search and rescue missions: [ [Link](#) ]
- 20.11.2020 - **IEEE Spectrum**, Flightmare simulator on IEEE Spectrum Video Friday: [ [Link](#) ]
- 18.11.2020 – **Robohub**, IROS2020 - Robohub interviews Davide Scaramuzza: [ [Link](#) ]
- 18.11.2020 - **Robotics Today**, Davide Scaramuzza invited speaker in Robotics Today: [ [Link](#) ]
- 20.10.2020 – **Overtake**, Perfect lap times with deep learning AI: [ [Link](#) ]
- 15.10.2020 – **RSI**, Interview of Davide Scaramuzza on robot ethics on Swiss Italian TV (RSI): [ [Link](#) ]
- 08.10.2020 - **IEEE Spectrum**, IEEE Spectrum. AI-Powered Drone Learns Extreme Acrobatics: [ [Link](#) ]
- 16.09.2020 - **Tech Xplore**, A deep learning model achieves super-human performance at Gran Turismo Sport: [ [Link](#) ]
- 14.09.2020 - **IEEE Spectrum**, IEEE Spectrum Video Friday: Super-Human Performance in GTS paper [ [Link](#) ]
- 14.09.2020 – **Synced**, Fast and Furious! DRL-Fuelled Agents Grab Pole Position in Gran Turismo Sport: [ [Link](#) ]
- 11.09.2020 – **WEIXIN**, Davide Scaramuzza featured in WEIXIN: [ [Link](#) ]
- 04.09.2020 - **IEEE Spectrum**, Our Flightmare simulator is featured in the IEEE Spectrum Video Friday: [ [Link](#) ]
- 04.09.2020 - **IEEE Spectrum**, IEEE Spectrum Video Friday: Our ICRA Workshop [ [Link](#) ]
- 24.07.2020 - **nextrends Asia**, Talking drones with Davide Scaramuzza: [ [Link](#) ]
- 15.07.2020 - **Vision Systems Design**, Unique image processing algorithms increase drone reaction speeds: [ [Link](#) ]
- 26.07.2020 - **Sim2realAI**, Deep Drone Acrobatics (Blog Post) [ [Link](#) ]
- 29.06.2020 - **Der Spiegel**, Akrobatische Drohnen [ [PDF](#) ]
- 25.06.2020 - **Drones Crunch**, Must Watch! Programming Precision Aerobatics [ [Link](#) ]
- 24.06.2020 – **NCYT**, Acrobacias para drones [ [Link](#) ]
- 24.06.2020 – **ZDNet**, An autonomous daredevil pushes the limits of flight [ [Link](#) ]



- 24.06.2020 – **DailyMail**, Drones all in a spin! AI algorithm enables quadcopters to perform acrobatic manoeuvres like power loops and barrel rolls autonomously [ [Link](#) ]
- 23.06.2020 – **Blick**, Navigationsalgorithmus der Uni Zurich lehrt Drohnen Kunststücke klein [ [Link](#) ]
- 24.06.2020 – **Robohub**, Drones learn acrobatics by themselves [ [Link](#) ]
- 24.06.2020 - **New Atlas**, AI algorithm enables autonomous drones to do barrel rolls and flips [ [Link](#) ]
- 24.06.2020 – **InceptiveMind**, A navigation algorithm enables drones to learn challenging acrobatic maneuvers [ [Link](#) ]
- 17.06.2020 – **DroneDj**, Drones trained to do acrobatics thanks to artificial intelligence [ [Link](#) ]
- 17.06.2020 - **IEEE Spectrum**, Debate on the Future of Robotics Research [ [Link](#) ]
- 12.06.2020 - **Venture Beat**, Researchers train drones to perform flips, rolls, and loops with AI [ [Link](#) ]
- 11.05.2020 – **Nature**, A drone ducks, dips and dives to dodge obstacles in a flash [ [Link](#) ]
- 11.05.2020 – **Gizmodo**, Thrown Rocks Are No Threat to These Drones That Have Mastered Dodgeball [ [Link](#) ]
- 11.05.2020 - **The RobotReport**, Drone detects & avoids obstacles in 3.5 milliseconds [ [Link](#) ]
- 11.05.2020 – **Robohub**, This drone can play dodgeball - and win [ [Link](#) ]
- 11.05.2020 – **SwissInfo**, Zürcher Forscher entwickeln extrem flink ausweichende Drohnen [ [Link](#) ]
- 11.05.2020 - **20 Minuten**, Diese Drohne besiegt uns sogar beim Völkerball [ [Link](#) ]
- 11.05.2020 – **Blick**, Zürcher Forscher entwickeln extrem flink ausweichende Drohnen [ [Link](#) ]
- 11.05.2020 - **UAS Vision**, Quadcopter Can Detect and Avoid Fast-Moving Objects [ [Link](#) ]
- 11.05.2020 - **Tech Ifeng**, Tech Ifeng coverage about our Science Robotics publication [ [Link](#) ]
- 11.05.2020 – **Sohu**, Sohu coverage about our Science Robotics publication [ [Link](#) ]
- 11.05.2020 - **Drones Magazin**, Wie eine Drohne beweglichen Hindernissen ausweichen kann [ [PDF](#) ]
- 16.04.2020 - **le Scienze Blog**, Droni: un aiuto che viene dal cielo [ [Link](#) ]
- 20.03.2020 - **SRF and 3Sat**, This documentary (German only) demonstrates our research on how autonomous drones can be used for search and rescue. (video starts at time 15:50) [ [Link](#) ]
- 09.01.2020 – **RSI**, Radio-Svizzera Italiana about the ERC Grant (starts at 15:30 minutes)[ [Link](#) ]
- 07.01.2020 – **Lockheed Martin**, Lockheed Martin coverage about the Alpha Pilot challenge [ [Link](#) ]
- 04.01.2020 – **AGEFI**, Deux millions pour les drones autonomes suisses [ [Link](#) ]

## 2019

- 10.12.2019 – **ERC Grant**, RPG awarded 2 million Euros from the European Research Council! [ [Link](#) ]
- 10.12.2019 – **UZH News**, UZH Drone Wins Silver in International Drone Racing Competition [ [Link](#) ]
- 30.11.2019 – **Wetten Dass**, "Wetten, dass...?" for our work on dodging obstacles [ [Link](#) ]
- 23.11.2019 – **IEEE Spectrum**, Robotic Endoscope Travels Through the Colon [ [Link](#) ]
- 20.11.2019 – **SRF**, Schweizer Drohnen auf amerikanischem Radar [ [Link](#) ]
- 16.11.2019 – **SRF**, Radio Interview (SRF Kultur) (start at 20:53). [ [Link](#) ]
- 20.10.2019 – **Tages Anzeiger**, Die Drohne, die sich selber faltet [ [PDF](#), [Online Article](#) ]
- 10.10.2019 – **NASA Tech Briefs**, Create the Future: A Drone That Folds to Fit Through Holes and Gaps [ [Link](#) ]
- 13.08.2019 – **BBC News**, Drones are able to change their shape while flying [ [Link](#) ]
- 12.08.2019 – **Robohub**, The future of rescue robotics [ [Link](#) ]
- 27.07.2019 – **E&T**, Evil genius: Fly, my pretties, fly! [ [Link](#) ]
- 27.07.2019 – **Blick.ch**, US-Rüstungskonzern scharf auf Schweizer Drohnentechologie [ [Link](#) ]
- 27.07.2019 – **KXAN36News**, Drones: University of Zurich at Lockheed-Martin-competition [ [Link](#) ]
- 29.07.2019 – **NZZ**, In der Forschung zu autonom fliegenden Drohnen spielt die Uni [ [Link](#) ]
- 12.07.2019 – **SwissInfo**, A Zurich, dans le fief suisse des Prix Nobel [ [Link](#) ]
- 09.07.2019 – **Engadget**, Watch super slow-mo video from a camera with human-like vision [ [Link](#) ]
- 09.07.2019 – **PetaPixel**, Scientists Use Camera with Human-Like Vision to Capture 5,400 fps Video [ [Link](#) ]
- 14.06.2019 – **UZH News**, Startklar für die Drohnen-Olympiade [ [Link](#) ]
- 04.06.2019 – **IEEE Spectrum**, To Fly Solo, Racing Drones Have a Need for AI Speed Training [ [Link](#) ]
- 29.05.2019 – **BBC**, Tech gives drone the ability to avoid mid-air crashes [ [Link](#) ]
- 20.05.2019 – **Tech Briefs**, Drone Uses Event Camera to Dodge Soccer Balls Thrown At It [ [Link](#) ]
- 26.05.2019 – **AUVSI**, University of Zurich researchers develop drone that can autonomously dodge objects [ [Link](#) ]
- 26.05.2019 – **UAV.org**, Zurich Researchers Teach Drone to Dodge with Dynamic Obstacle Avoidance [ [Link](#) ]
- 26.05.2019 – **Drone-Zone.de**, Du triffst nicht! "Drohne weicht automatisch Bällen aus" [ [Link](#) ]
- 22.05.2019 – **PR Newswire**, Lockheed Martin and Drone Racing League Announce 2019 AlphaPilot Teams [ [Link](#) ]
- 17.05.2019 – **Digital Trends**, Watch this drone dodge an incoming soccer ball autonomously [ [Link](#) ]
- 17.05.2019 – **BoingBoing.net**, Watch this drone dodge soccer balls hurled at it [ [Link](#) ]
- 16.05.2019 – **La Repubblica**, L'intervista - Davide Scaramuzza: "Ma devo imparare a muoversi da soli" [ [Link](#) ]
- 16.05.2019 – **Business Insider**, Watch this self-piloting drone effortlessly dodge a soccer ball being thrown at it [ [Link](#) ]
- 16.05.2019 – **CBS**, This drone would be great at dodge-ball [ [Link](#) ]
- 16.05.2019 – **Fox News**, Watch an autonomous drone dodge thrown objects [ [Link](#) ]
- 16.05.2019 – **PCMag**, Watch an Autonomous Drone Dodge Thrown Objects [ [Link](#) ]
- 16.05.2019 – **SFGate**, Watch this self-piloting drone effortlessly dodge a soccer ball being thrown at it in real-time [ [Link](#) ]
- 16.05.2019 – **CNET**, Watch this drone dodge a ball [ [Link](#) ]
- 16.05.2019 – **Drone Life**, Zurich Researchers Teach Drone to Dodge with Dynamic Obstacle Avoidance [ [Link](#) ]
- 16.05.2019 – **The Verge**, Watch an autonomous drone dodge, duck, dip, dive, and dodge a football [ [Link](#) ]
- 13.05.2019 – **IEEE Spectrum**, Event Camera Helps Drone Dodge Thrown Objects [ [Link](#) ]
- 07.05.2019 – **Reuters**, Europe's Most Innovative Universities 2019 [ [Link](#) ]
- 27.03.2019 – **The New York Times**, A.I. Is Flying Drones (Very, Very Slowly) [ [Link](#) ]

- 28.02.2019 – **Business Insider Italia**, Lockheed Martin lancia la corsa piú pazza del mondo 2.0 [ [Link](#) ]
- 28.02.2019 – **UZH Journal**, Faltbare und lernbereite Drohnen [ [Link](#) ]
- 27.02.2019 – **IEEE Innovate**, Neural Network Teaches Drones to Navigate Cities Autonomously [ [Link](#) ]
- 18.02.2019 – **CNBC**, Self-folding drone could speed up search and rescue missions [ [Link](#) ]
- 19.01.2019 – **Tages Anzeiger**, Flughafen Zürich baut Drohnenschutz aus [ [Link](#) ]
- 02.01.2019 – **HWZ Hochschule**, Drohne kommt überall durch [ [Link](#) ]

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- 20.12.2018 – **The Verge**, A shape-shifting drone suggests the future of rescue missions [ [Link](#) ]
- 19.12.2018 – **Il Fatto Quotidiano**, Il drone da soccorso che piega le ali come gli uccelli [ [Link](#) ]
- 16.12.2018 – **Robohub**, A new drone can change its shape to fly through a narrow gap [ [Link](#) ]
- 14.12.2018 – **TechCrunch**, This drone shrinks to fit [ [Link](#) ]
- 14.12.2018 – **CNET**, Foldable drone can fit through tight spaces [ [Link](#) ]
- 14.12.2018 – **Arduino.cc**, Drone morphs into the perfect shape in mid-air [ [Link](#) ]
- 14.12.2018 – **Drone Life**, Agile Drones that Fold to get Through Tight Spaces [ [Link](#) ]
- 14.12.2018 – **ANSA**, Il drone uccello, cambia forma in volo [ [Link](#) ]
- 14.12.2018 – **La Repubblica**, Droni con 'ali pieghevoli' per passare ovunque [ [Link](#) ]
- 14.12.2018 – **Libero.it**, Drone pieghevole, cambia forma in volo [ [Link](#) ]
- 14.12.2018 – **Drone Life**, Agile Drones that Fold to get Through Tight Spaces [ [Link](#) ]
- 14.12.2018 – **Gadgets Now**, This foldable drone can squeeze through narrow gaps [ [Link](#) ]
- 14.12.2018 – **Tages Anzeiger**, Diese Drohne kommt überall durch [ [Link](#) ]
- 14.12.2018 – **AS.com**, Este dron puede encogerse y agrandarse en pleno vuelo [ [Link](#) ]
- 13.12.2018 – **IEEE Spectrum**, Foldable Drone Changes Its Shape in Mid-Air [ [Link](#) ]
- 13.12.2018 – **Popular Mechanics**, This Foldable Drone Is a Flying Transformer [ [Link](#) ]
- 13.12.2018 – **The Economic Times**, New foldable drone can squeeze through narrow gaps [ [Link](#) ]
- 13.12.2018 – **10 Daily**, Foldable Drone Could Help Find Survivors Of Natural Disasters [ [Link](#) ]
- 13.12.2018 – **Microsiervos**, Un cuadricoptero que se pliega en el aire para entrar en sitios estrechos [ [Link](#) ]
- 13.12.2018 – **Financial Express**, New foldable drone can squeeze through narrow gaps [ [Link](#) ]
- 13.12.2018 – **RTS**, Des chercheurs suisses developpent un drone capable de replier ses ailes [ [Link](#) ]
- 12.12.2018 – **ScienceDaily**, New foldable drone flies through narrow holes in rescue missions [ [Link](#) ]
- 12.12.2018 – **Technology.org**, New Foldable Drone Flies through Narrow Holes in Rescue Missions [ [Link](#) ]
- 12.12.2018 – **Tech Explorer**, New foldable drone flies through narrow holes in rescue missions [ [Link](#) ]
- 12.12.2018 – **RSI**, Un drone... pieghevole [ [Link](#) ]
- 12.12.2018 – **SlashGear**, Folding rescue drone can transform its shape while in the air [ [Link](#) ]
- 12.12.2018 – **20 minutes**, Un drone pliable pour des missions de sauvetage [ [Link](#) ]
- 12.12.2018 – **ComputerWorld**, Drohne fliegt durch enge Löcher [ [Link](#) ]
- 12.12.2018 – **Blick**, Drohne macht sich klein für Flug durch enge Spalten und Löcher [ [Link](#) ]
- 12.12.2018 – **Netzwoche**, Neue faltbare Drohne fliegt durch enge Löcher zu Einsturzopfern [ [Link](#) ]
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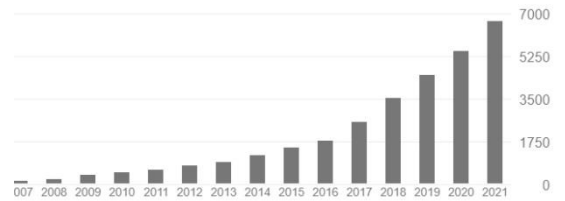
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Scholar H-index: 93

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## OPEN-SOURCE SOFTWARE AND DATASETS

I released **86 open-source software packages, datasets, and toolboxes**. The full list can be found here:

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- [153] A. Loquercio, **D. Scaramuzza**, Learning to Control Drones in Natural Environments: A Survey, *ICRA18 Workshop on Perception, Inference, and Learning*, Brisbane, 2018.
- [154] Z. Zhang, **D. Scaramuzza**, A Tutorial on Quantitative Trajectory Evaluation for Visual(-Inertial) Odometry, *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Madrid, 2018.
- [155] D. Falanga, P. Foehn, P. Lu, **D. Scaramuzza**, PAMPC: Perception-Aware Model Predictive Control for Quadrotors, *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Madrid, 2018.
- [156] G. Gallego, H. Rebecq, **D. Scaramuzza**, A Unifying Contrast Maximization Framework for Event Cameras, with Applications to Motion, Depth and Optical Flow Estimation, *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Salt Lake City, 2018, **Oral Spotlight Presentation.**
- [157] A.I. Maqueda, A. Loquercio, G. Gallego, N. Garcia, **D. Scaramuzza**, Event-based Vision meets Deep Learning on Steering Prediction for Self-driving Cars, *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, Salt Lake City, 2018.
- [158] T. Cieslewski, S. Choudhary, **D. Scaramuzza**, Data-Efficient Decentralized Visual SLAM, *IEEE International Conference on Robotics and Automation (ICRA)*, 2018.
- [159] Z. Zhang, **D. Scaramuzza**, Perception-aware Receding Horizon Navigation for MAVs, *IEEE International Conference on Robotics and Automation (ICRA)*, 2018.
- [160] J. Delmerico, **D. Scaramuzza**, A Benchmark Comparison of Monocular Visual-Inertial Odometry Algorithms for Flying Robots, *IEEE International Conference on Robotics and Automation (ICRA)*, 2018.

- [161] P. Foehn, **D. Scaramuzza**, Onboard State Dependent LQR for Agile Quadrotors, *IEEE International Conference on Robotics and Automation (ICRA)*, 2018.
- [162] R. Gomez-Ojeda, Z. Zhang, J. Gonzalez-Jimenez, **D. Scaramuzza**, Learning-based Image Enhancement for Visual Odometry in Challenging HDR Environments, *IEEE International Conference on Robotics and Automation (ICRA)*, 2018.
- [163] T. Cieslewski, **D. Scaramuzza**, Efficient Decentralized Visual Place Recognition from Full-Image Descriptors, *MRS 2017: the 1st International Symposium on Multi-Robot and Multi-Agent Systems*, Los Angeles, Dec. 2017
- [164] E. Mueggler, C. Bartolozzi, **D. Scaramuzza**, Fast Event-based Corner Detection, *British Machine Vision Conference*, 2017.
- [165] Y. Ye, T. Cieslewski, **D. Scaramuzza**, Place Recognition in Semi-Dense Maps, *Fast Event-based Corner Detection, British Machine Vision Conference*, 2017.
- [166] H. Rebecq, T. Horstschaefler, **D. Scaramuzza**, Real-time Visual-Inertial Odometry for Event Cameras using Keyframe-based Nonlinear Optimization, *British Machine Vision Conference*, 2017. **Oral Presentation. Acceptance Rate: 5.6%**
- [167] D. Falanga, A. Zanchettin, A. Simovic, J. Delmerico, **D. Scaramuzza**, Vision-based Autonomous Quadrotor Landing on a Moving Platform, *IEEE/RSJ International Symposium on Safety, Security and Rescue Robotics (SSRR)*, Shanghai, 2017.
- [168] T. Cieslewski, E. Kaufmann, **D. Scaramuzza**, Rapid Exploration with Multi-Rotors: A Frontier Selection Method for High Speed Flight, *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Vancouver, 2017. **IROS'17 Best Search and Rescue Robotics Paper Award Finalist.**
- [169] P. Foehn, D. Falanga, N. Kuppuswamy, R. Tedrake, **D. Scaramuzza**, Fast Trajectory Optimization for Agile Quadrotor Maneuvers with a Cable-Suspended Payload, *Robotics: Science and Systems (RSS)*, Boston, 2017. **Best Student Paper Award Finalist. Oral Presentation. Acceptance rate: 4%**
- [170] V. Vasco, A. Glover, E. Mueggler, **D. Scaramuzza**, L. Natale, C. Bartolozzi, Independent Motion Detection with Event-driven Cameras, *International Conference on Advanced Robotics (ICAR)*, Hong Kong, 2017.
- [171] Z. Zhang, C. Forster, **D. Scaramuzza**, Active Exposure Control for Robust Visual Odometry in HDR environments, *IEEE International Conference on Robotics and Automation*, 2017.
- [172] D. Falanga, E. Mueggler, M. Faessler, **D. Scaramuzza**, Aggressive Quadrotor Flight through Narrow Gaps with Onboard Sensing and Computing, *IEEE International Conference on Robotics and Automation*, 2017.
- [173] M. Gassner, T. Cieslewski, **D. Scaramuzza**, Dynamic Collaboration without Communication: Vision-Based Object Transport with Two Quadrotors, *IEEE International Conference on Robotics and Automation*, 2017.
- [174] R. Kaeslin, P. Fankhauser, E. Stumm, Z. Taylor, E. Mueggler, J. Delmerico, **D. Scaramuzza**, R. Siegwart, M. Hutter Collaborative Localization of Aerial and Ground Robots through Elevation Maps, *International Symposium on Safety, Security, and Rescue Robotics (SSRR)*, Lausanne, 2016.
- [175] H. Rebecq, G. Gallego, **D. Scaramuzza**, EMVS: Event-based Multi-View Stereo, *British Machine Vision Conference (BMVC)*, York, 2016. **Oral acceptance rate: 7%, Best Industry Paper Award.**
- [176] J. Delmerico, A. Giusti, E. Mueggler, L.M. Gambardella, **D. Scaramuzza**, "On-the-spot Training" for Terrain Classification in Autonomous Air-Ground Collaborative Teams, *International Symposium on Experimental Robotics (ISER)*, Tokyo, 2016.
- [177] B. Kueng, E. Mueggler, G. Gallego, **D. Scaramuzza**, Low-Latency Visual Odometry using Event-based Feature Tracks, *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Daejeon, 2016. **Best Application Paper Award Finalist! Highlight Talk: Acceptance Rate 2.5%**
- [178] D. Tedaldi, G. Gallego, E. Mueggler, **D. Scaramuzza**, Feature Detection and Tracking with the Dynamic and Active-pixel Vision Sensor (DAVIS), *International Conference on Event-Based Control, Communication and Signal Processing (EBCCSP)*, Krakow, 2016.
- [179] C. Braendli, J. Strubel, S. Keller, **D. Scaramuzza**, T. Delbruck, ELiSeD - An Event-Based Line Segment Detector, *International Conference on Event-Based Control, Communication and Signal Processing (EBCCSP)*, Krakow, 2016.
- [180] S. Isler, R. Sabzevari, J. Delmerico, D. Scaramuzza, An Information Gain Formulation for Active Volumetric 3D Reconstruction, *IEEE International Conference on Robotics and Automation (ICRA)*, Stockholm, 2016.
- [181] Z. Zhang, H. Rebecq, C. Forster, **D. Scaramuzza**, Benefit of Large Field-Of-View Cameras for Visual Odometry, *IEEE International Conference on Robotics and Automation (ICRA)*, 2016.

- [182] G. Costante, J. Delmerico, M. Werlberger, P. Valigi, **D. Scaramuzza**, Online, Perception-aware Path Planning, *International Symposium on Robotics Research (ISRR)*, Sestri Levante, Sep. 2015.
- [183] C. Forster, L. Carlone, F. Dellaert, **D. Scaramuzza**, IMU Preintegration on Manifold for Efficient Visual-Inertial Maximum-a-Posteriori Estimation, *Robotics: Science and Systems (RSS)*, 2015. **Best Paper Award finalist. Oral Presentation. Acceptance rate: 4%.**
- [184] E. Mueggler, N. Baumli, F. Fontana, D. Scaramuzza, Towards Evasive Maneuvers with Quadrotors using Dynamic Vision Sensors, *European Conference on Mobile Robots (ECMR)*, Lincoln, 2015.
- [185] E. Mueggler, G. Gallego, **D. Scaramuzza**, Continuous-Time Trajectory Estimation for Event-based Vision Sensors, *Robotics: Science and Systems (RSS)*, 2015.
- [186] M. Faessler, F. Fontana, C. Forster, **D. Scaramuzza**, Automatic Re-Initialization and Failure Recovery for Aggressive Flight with a Monocular Vision-Based Quadrotor, *IEEE International Conference on Robotics and Automation (ICRA)*, 2015.
- [187] E. Mueggler, C. Forster, N. Baumli, G. Gallego, **D. Scaramuzza**, Lifetime Estimation of Events from Dynamic Vision Sensors, *IEEE International Conference on Robotics and Automation (ICRA)*, 2015.
- [188] C. Forster, M. Faessler, F. Fontana, M. Werlberger, **D. Scaramuzza**, Continuous On-Board Monocular-Vision-based Aerial Elevation Mapping for Quadrotor Landing, *IEEE International Conference on Robotics and Automation (ICRA)*, 2015
- [189] E. Mueggler, M. Faessler, F. Fontana, **D. Scaramuzza**, Aerial-guided Navigation of a Ground Robot among Movable Obstacles, *IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR)*, Toyako-cho, 2014.
- [190] C. Forster, M. Pizzoli, **D. Scaramuzza**, Appearance-based Active, Monocular, Dense Reconstruction for Micro Aerial Vehicles, *Robotics: Science and Systems (RSS)*, Berkely, 2014.
- [191] Mueggler, E., Faessler, M., Fontana, F., **Scaramuzza, D.**, Aerial-guided Navigation of a Ground Robot among Movable Obstacles, *IEEE International Symposium on Safety, Security, and Rescue Robotics*, 2014.
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- [193] E. Mueggler, B. Huber, D. Scaramuzza, Event-based, 6-DOF Pose Tracking for High-Speed Maneuvers, 2014 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Chicago, 2014.
- [194] Reza Sabzevari, **D. Scaramuzza**, Monocular Simultaneous Motion Segmentation and Reconstruction in Urban Environments, *IEEE International Conference on Robotics and Automation (ICRA)*, 2014
- [195] M. Faessler, E. Mueggler, K.S. Schwabe, **D. Scaramuzza**, A Monocular Pose Estimation System based on Infrared LEDs, *IEEE International Conference on Robotics and Automation (ICRA)*, 2014
- [196] Y. Jiang, **D. Scaramuzza**, ICP Stereo Visual Odometry for Wheeled Vehicles based on a 1DOF Motion Prior, *IEEE International Conference on Robotics and Automation (ICRA)*, 2014
- [197] C. Troiani, A. Martinelli, C. Laugier, **D. Scaramuzza**, 2-Point-based Outlier Rejection for Camera-IMU Systems with applications to Micro Aerial Vehicles, *IEEE International Conference on Robotics and Automation (ICRA)*, 2014
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- [200] A. Censi, **D. Scaramuzza**, Low-latency event-based visual odometry, *IEEE International Conference on Robotics and Automation (ICRA)*, 2014
- [201] Forster, Pizzoli, **D. Scaramuzza**, Air-Ground Localization and Map Augmentation Using Monocular Dense Reconstruction, *IEEE/RSJ International Conference on Intelligent Robots and Systems, IROS'13*, 2013.
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#### MASTER THESIS

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**This thesis won the Italian best Master thesis award (AICA-FEDERCOMIN award) in 2005, conferred by the Italian Minister of Innovation.**